# An Optimized Decision Algorithm for Stratified Context Unification 

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#### Abstract

Context unification is a variant of second order unification. It can also be seen as a generalization of string unification to tree unification. Currently it is not known whether context unification is decidable. A specialization of context unification is stratified context unification, which is decidable. However, the previous algorithm has a very bad worst case complexity. Recently it turned out that stratified context unification is equivalent to satisfiability of one-step rewrite constraints. This paper contains an optimized algorithm for stratified context unification exploiting sharing and power expressions. We prove that the complexity is determined mainly by the maximal depth of SO-cycles. Two observations are used: i. For every ambiguous SO-cycle, there is a context variable that can be instantiated with a ground context of main depth $O(c * d)$, where $c$ is the number of context variables, and $d$ is the depth of the SO-cycle. ii. the exponent of periodicity is $O\left(2^{n}\right)$, which means it has an $O(n)$ sized representation. From a practical point of view, these observations allow us to conclude that the unification algorithm is well-behaved, if the maximal depth of SO-cycles does not grow too large.


## 1 Introduction

Context unification is a variant of second order unification and also a generalization of string unification. There are unification procedures for the more general problem of higher-order unification (see e.g. [Pie73,Hue75,SG89,Wol93,Pre95]). It is well-known that general higher-order unification and second-order unification are undecidable [Gol81,Far91,LV99] and that string unification is decidable [Mak77]. Recent upper complexity estimations for string unification are NEXPTIME [Pla99a] and PSPACE [Pla99b].

Context unification problems are restricted second-order unification problems: context variables represent terms with exactly one hole in contrast to a term with an arbitrary number of (equally named) holes in the general case. The name contexts was coined in [Com93]. Currently, it is not known whether general context unification is decidable. There are some decidable fragments:

If the number of occurrences of every first order variable and context variable is at most two [Lev96], or if there are at most two context variables, but an arbitrary number of first order variables [SSS99], or if the context unification problems are stratified [SS99b]. Satisfiability in a logical theory of context unification is undecidable [NPR97,Vor98]. A decidable restriction of second order unification similar in spirit to context unification is bounded second order unification [SS99a], where second order variables represent terms with a number of holes that is bounded by some preselected number.

Applications of context unification are for example in computational linguistics [NPR97] and of (stratified) context unification in equational unification [SS98]. Recently it was noticed that satisfiability of one-step rewrite constraints and stratified context unification can be interreduced [NTT99].

This paper presents an algorithm for stratified context unification that improves the run time and space usage of the decision algorithm given in [SS99b]. Based on the methods in [SS99b] a proof of an estimation of the complexity of SCUA is given:

Theorem: Stratified context unification can be performed in time polynomial in the size of the input and the depth of SO-cycles.

It follows from [NTT99] that the algorithm can be traslated and hence the complexity estimation holds also for satisfiability of one-step rewrite constraints.

The construction of the algorithm SCUA and the upper bounds have consequences for implementations. It demonstrates that the exploitation of sharing and the compression of iterated contexts is useful. Unfortunately, we were not able to give an upper bound on the depth of SO-cycles. On the other hand, we have found no example that has SO-cycles during the transformation algorithm of more than linear depth. This supports the conjecture that the depth of SO-cycles is small (perhaps polynomial).

## 2 Preliminaries

Let $\Sigma$ be a signature, where we assume that the signature contains at least one non-constant function symbol, in particular we allow also that the signature may be infinite or monadic. With $\operatorname{ar}(f)$ we denote the arity of the function symbol $f$. Let $\mathcal{V}_{1}$ be the set of first order variables $x, y, z, \ldots, \mathcal{V}_{2}$ be the set of context variables $X, Y, Z, \ldots$, and $\mathcal{V}:=\mathcal{V}_{1} \cup \mathcal{V}_{2}$. Terms are formed like first order terms, where context variables are unary and may occur in the position of function symbols. First order terms are terms without occurrences of holes and context variables. If we mean a first order context variable, we write $\mathcal{X}$. Contexts are first order terms with a single occurrence of the special constant $\cdot$, the hole. We denote contexts as $C[\cdot]$. The path from the root to the hole of $C$ is called main path, denoted $m p(C)$; the length is called main depth and denoted as $m d t(C)$. With $I d$ we denote the empty (or trivial) context. A prefix of a context $C$ is a context $C_{1}$, such that $C_{1} C_{2}=C$ for some context $C_{2}$.

Substitutions $\sigma$ replace first order variables by first order terms and context variables by contexts. We also use multi-contexts $C\left[{ }_{1}, \ldots,{ }_{n}\right]$, which are first order terms with occurrences of the holes $\cdot 1, \ldots, \cdot n$, where every hole occurs exactly once. As is standard, positions in terms and contexts are words of positive integers, and $\left.t\right|_{p}$ denotes the subterm (subcontext) of $t$ at position $p$.

In the following we sometimes use the notation $C[\cdot]^{n}$, where $C[\cdot]$ is a context and $n$ is an integer. This is defined as $C[\cdot]^{1}:=C[\cdot], C[\cdot]^{n+1}:=C\left[C[\cdot]^{n}\right]$. If we use this notation in a term, it is meant as a meta-notation of a term, not as explicit syntax. For integers we use $i \bmod * n$, which is the unique number $j \in[1 . . n]$ with $i \equiv j(\bmod n)$.
An equation system is a set of equations $s \doteq t$, also called unification problem.
A ground substitution $\sigma$ has exponent of periodicity $n$ ([Mak77,SSS98]), iff i) for every $\mathcal{X}$, if there are ground contexts $A, B, C$ with $B$ nontrivial, such that $\sigma(\mathcal{X})=A B^{m} C$, then $m \leq n$; ii) there is some $\mathcal{X}$, such that $\sigma(\mathcal{X})=A B^{n} C$, for appropriate ground contexts $A, B, C$ where $B$ is nontrivial.

The following lemma is a generalization of [KP96].
Lemma 2.1. ([SSS98]) There is a constant $c$, such that for every unifiable context unification problem $\Gamma$ its exponent of periodicity is at most $2^{c * d}$, where $d$ is the size of $\Gamma$.

Definition 2.2. We define SO-prefixes as words in $\mathcal{V}_{2}^{*}$. An SO-prefix of a position $p$ in a term $t$ is the word consisting of the context variables in head positions that are met going from the root to the position $p$.

In an equation system $\Gamma$, an SO-prefix of a variable or context variable $\mathcal{X}$ is a word in $\mathcal{V}_{2}^{*}$, that either belongs to an equation $s \doteq t$, and a position of $\mathcal{X}$ in $t$ or $s$; or it belongs to a path $x_{1} \doteq t_{1}, \ldots, x_{n} \doteq t_{n}$ and is constructed as $w:=w_{1} \ldots w_{n}$, where $w_{i}$ is the SO-prefix of some position of $x_{i+1}$ in $t_{i}$ for $1 \leq i<n$ and $w_{n}$ is the SO-prefix of some position of $\mathcal{X}$ in $t_{n}$. An SO-prefix is maximal, if it either belongs to an occurrence in $s \doteq t$, and $s, t$ are not variables, or to a path $x_{1} \doteq t_{1}, \ldots, x_{n} \doteq t_{n}$ and every occurrence of $x_{1}$ has an empty SO-prefix.

Let the following hold:

1. for every variable and context variable $\mathcal{X}$, there exists a finite unique maximal SO-prefix $p(\mathcal{X})$, and
2. for every equation $C[\mathcal{X}] \doteq D[\mathcal{Y}] \in \Gamma$ the following holds: let the SO-prefixes of $\mathcal{X}, \mathcal{Y}$ in the terms $C[\mathcal{X}], C[\mathcal{Y}]$ be $p_{\mathcal{X}}, p_{\mathcal{Y}}$. Then $p_{\mathcal{X}}=p_{\mathcal{Y}}$ implies that the maximal $S O$-prefixes in $\Gamma$ of $\mathcal{X}$, and $\mathcal{Y}$ are equal.

Then $\Gamma$ is called stratified.
This definition is consistent with the definitions in [SS94,SS99b,Lev96], but it is adapted to systems of equations that permit equations like $x=y, X(x)=$ $z$. i.e., that variables may have different SO-prefix in the terms that occur in equations. It is consistent with this definition to consider equations as labeled with an SO-prefix, and then use the label of the equation and the SO-prefix of positions in terms to compute the SO-prefix in $\Gamma$.

For example, $X(x) \doteq x$ is not permitted, since there is no finite SO-prefix of $x ; X(x) \doteq Y(x)$ is not stratified, but $X(x) \doteq Y(y), x \doteq f(z)$ is stratified.

## 3 The algorithm SCUA

The initial input is a set of equations. The intermediate data structure is more involved: Let a skeleton context $B$ be a context of the form $B_{1} \ldots B_{m}$, where $B_{i}$ is of the form $f\left(x_{1}, \ldots, x_{j_{i}-1}, \cdot, x_{j_{i}+1}, \ldots, x_{n}\right)$. With $|B|$ we denote the main depth of $B$. Let a power expression be $\operatorname{pow}(B, n)$, where $n \geq 0$, and $B$ is a skeleton context. Let the terms be $\boldsymbol{x}\left|f\left(t_{1}, \ldots, t_{n}\right)\right| X(t) \mid P(t)$ where $\boldsymbol{x}$ is a variable, $f$ a function symbol of arity $n, X$ a context variable, $t, t_{i}$ are terms, and $P$ is a power expression. $\operatorname{pow}(B, n)(x)$ is a syntactically compressed form of $B^{n_{1}} C(x)$, where $n=n_{1} *|B|+n_{2}$ with $n_{1} \geq 0,0 \leq n_{2}<|B|$ and $C$ is a prefix of $B$ with $m d t(C)=n_{2}$.

Let $\operatorname{head}(\cdot)$ be defined as: $\operatorname{head}(x):=x, \operatorname{head}(f(\ldots)):=f, \operatorname{head}(Y(y)):=Y$, $\operatorname{head}\left(\operatorname{pow}\left(f(\ldots) \ldots B_{m}, n\right)(s)\right):=f$ if $n \geq 1$.
$\operatorname{shift}\left(B_{1} \ldots B_{n}, m\right)$ is defined as: $\operatorname{shift}\left(B_{1} \ldots B_{n}, 0\right):=B_{1} \ldots B_{n}$ and $\operatorname{shift}\left(B_{1} \ldots B_{n}, m\right):=\operatorname{shift}\left(B_{2} \ldots B_{n} B_{1}, m-1\right)$.
Let expand $\left(\operatorname{pow}\left(B_{1} \ldots B_{m}, n\right)\right)$ be defined as follows:
$\operatorname{expand}\left(\operatorname{pow}\left(B_{1} \ldots B_{m}, 0\right)\right):=I d$, and
$\operatorname{expand}\left(\operatorname{pow}\left(B_{1} \ldots B_{m}, n\right)\right):=B_{1}\left(\operatorname{expand}\left(\operatorname{pow}\left(B_{2} \ldots B_{m} B_{1}, n-1\right)\right)\right)$.
This is also used for terms: $\operatorname{expand}(\operatorname{pow}(B, n)(x)):=\operatorname{expand}(\operatorname{pow}(B, n))(x)$.
If we say a variable occurs in $\operatorname{pow}(B, n)$, then we mean the occurrences in $\operatorname{expand}(\operatorname{pow}(B, n))$.

A stratified context unification problem (SCUP) is a stratified system of context equations $\Gamma$, where equations are denoted as $s \doteq t$ plus a set of disequations of the form $X \neq I d$. A substitution $\sigma$ that maps first order variables to ground terms and context variables to ground contexts is a unifier (or a solution) of the SCUP $\Gamma$ iff after applying $\sigma$ and expand, the left and right hand sides of equations are syntactically equal, and for $(X \neq I d) \in \Gamma: \sigma(X) \neq I d$.

The algorithm SCUA has an initial input $\Gamma_{I}$. Let $D_{I}$ be the size of $\Gamma_{I}$, let $E_{I}$ be the upper bound on the exponent of periodicity given by the bound in [SSS98] for $\Gamma_{I}$, let $D_{A}:=\max \{2, \operatorname{ar}(f)\}$, where $f$ are the function symbols occurring in the initial input, and let $\#(C V)$ be the number of context variables in $\Gamma_{I}$.

The main technical advantages of SCUA over the algorithms in [SS99b] is the use of sharing by flattening equations, and the compressed representation of iterated contexts by power expressions. This forces to adapt the algorithm and to use new rules that operate on the new syntax.

### 3.1 Flattening

Initially, and after a replacement of context variables, a flattening may be required:

Definition 3.1. Rule (Flatten)

$$
\begin{aligned}
& -\frac{\{s \doteq t\} \cup \Gamma}{\{s \doteq x, x \doteq t\} \cup \Gamma \quad \text { if neither } s \text { nor } t \text { is a variable. }} \\
& -\frac{\left\{f\left(s_{1}, \ldots, s_{n}\right) \doteq t\right\} \cup \Gamma}{\left\{f\left(x_{1}, \ldots, x_{n}\right) \doteq t, x_{1} \doteq s_{1}, \ldots x_{n} \dot{\doteq} s_{n}\right\} \cup \Gamma \quad \text { if some } s_{i} \text { is not a variable. }} \\
& -\frac{\{X(s) \doteq t\} \cup \Gamma}{\{X(x) \doteq t, x \doteq s\} \cup \Gamma} \quad \text { if } s \text { is not a variable. } \\
& -\frac{\{p o w(B, n)(s) \doteq t\} \cup \Gamma}{\{p o w(B, n)(x) \doteq t, x \doteq s\} \cup \Gamma} \quad \text { if } s \text { is not a variable. }
\end{aligned}
$$

Here the introduced variables are alway fresh ones.
If the flattening rules are not applicable, then $\Gamma$ is called flattened. In this case, only terms of the form $x\left|f\left(x_{1}, \ldots, x_{n}\right)\right| X(x) \mid \operatorname{pow}(B, n)(x)$ where $x, x_{i}$ are variables, are permitted.

Definition 3.2. Rule (Normalizing Power Expressions)
A power expression pow $(B, n)(x)$ is replaced by pow $\left(C_{1} \ldots C_{k}, n * m\right)(x)$, if $B=\underbrace{C_{1} \ldots C_{k} C_{1} \ldots C_{k} \ldots C_{1} \ldots C_{k}}_{m \text { times }}$

In the following we assume that SCUPs are flattened and that power expressions are normalized.

### 3.2 Decomposition Rules

Definition 3.3. (decomposition rules)

1. (variable replacement): $\frac{\{x \doteq y\} \cup \Gamma}{\Gamma[y / x]}$.
2. (decomposition) $\frac{\left\{x \doteq f\left(x_{1}, \ldots, x_{n}\right), x \doteq f\left(y_{1}, \ldots, y_{n}\right)\right\} \cup \Gamma}{\left\{x \doteq f\left(x_{1}, \ldots, x_{n}\right), x_{1} \doteq y_{1}, \ldots, x_{n} \doteq y_{n}\right\} \cup \Gamma}$
3. (clash) $\quad \frac{\left\{x \doteq f\left(x_{1}, \ldots, x_{n}\right), x \doteq g\left(y_{1}, \ldots, y_{m}\right)\right\} \cup \Gamma}{\text { Fail }}, \quad$ if $f \neq g$.
4. (occurs-check) Fail, if there is a chain of equations $x_{1} \doteq t_{1}, \ldots, x_{n} \doteq t_{n}$, and $x_{i+1} \operatorname{mod*}{ }_{n}$ occurs in $t_{i}$, and at least one $t_{i}$ has a function symbol as head.
5. (remove-fo) $\frac{\{x \doteq x\} \cup \Gamma}{\Gamma_{X}}$.
6. Remove disequations $X \neq I d$, if $X$ does not occur in the rest of $\Gamma$.
7. $\frac{\{x \doteq t\} \cup \Gamma}{\Gamma}$ if $x$ does not occur in $t$ nor $\Gamma$.
8. (Remove-cv) For a context variable $X$, if $(X \neq I d) \notin \Gamma$, then select one of the following possibilities:
(a) Add the disequation $X \neq I d$.
(b) Replace $X$ by Id everywhere in $\Gamma$.

For every equation system $\Gamma$, the decomposition rules are performed with high priority. If no decomposition rule is applicable, then we say $\Gamma$ is decomposed. If for every context variable in $\Gamma$, there is a disequation $X \neq I d$, then we say it is disequation-complete.

### 3.3 SO-cycles and SO-clusters

Definition 3.4. A set of equations $s_{1} \dot{\doteq} t_{1}, \ldots, s_{n} \dot{\doteq} t_{n}$ is called an SO-cycle, if the following holds: $s_{i}$ is of the form $x_{i}\left(\right.$ or $X_{i}\left(y_{i}\right)$ ), and $x_{i}$ (or $X_{i}$ ) occurs in $t_{i-1}$ mod* $n$, but not below a context variable, and at least one such occurrence is not at the top, and there is no context variable that occurs twice in the SO-cycle. The length of an SO-cycle is the number of context variables at the top positions. An SO-cycle is called ambiguous, iff one of the following holds:

- There is an $i$, such that $s_{i}$ is a first order variable, and has more than one occurrence in $t_{i-1 \text { mod* } n \text {. }}$.
- For some $i$, the term $s_{i}$ is a first order variable, and the sequence of equations to the next context variable is $s_{i} \doteq t_{i}, \ldots, s_{j} \doteq t_{j}, t_{j}$ contains the context variable $X$, and the sequence can be replaced by a different subsequence starting with $s_{i} \doteq s_{i}^{\prime}$, ending with $s_{k}^{\prime} \doteq t_{k}^{\prime}$, the only term in the new subsequence that contains a context variable is $t_{k}^{\prime}$, and this context variable is $X$. Let the term $\bar{s}_{i}$ result from instantiating the variables using $s_{i} \doteq t_{i}, \ldots, s_{j} \doteq t_{j}$, and $\bar{s}^{\prime}{ }_{i}$ resulting from instantiating the variables using $s_{i} \doteq t_{i}^{\prime}, \ldots, s_{k}^{\prime} \doteq t_{k}^{\prime}$, and let the positions of the $X$ in the terms $\bar{s}_{i}$ and $\bar{s}_{i}$ be different.

The SO-cycle that results from such a replacement of one subsequence by athe other is called an ambiguous variant.

If the SO-cycle is not ambiguous, then it is called path-unique. The depth
 depth of an ambiguous $S O$-cycle is the maximum of the two smallest depths of two ambiguous variants of the SO-cycle.

Given the initial input $\Gamma_{I}$, let $D_{Z}$ be the maximum of the depth of all SOcycles that remains a maximum for all transformations.

Definition 3.5. Let $\Gamma$ be an SCUP. Let $\sim$ be the equivalence relation on $\mathcal{V}$ generated by $X_{1} \sim X_{2}, X_{1} \sim x_{1}$, or $x_{1} \sim y_{1}$ if there is an equation $X_{1}\left(z_{1}\right) \doteq$ $X_{2}\left(z_{2}\right), X_{1}\left(z_{3}\right) \doteq x_{1}$, or $x_{1} \doteq y_{1}$, respectively in $\Gamma$.

Let $\succ$ be the relation on $\mathcal{V}$ generated by $x \succ y$ if $x, y$ have empty SO-prefix and there is an equation $x \doteq t \in \Gamma, t \not \equiv x$ and $x$ occurs in $t$. I.e. $t \equiv f(\ldots, y, \ldots)$, or $t$ is of the form pow $(B, n)(z)$. Let $\gtrsim$ be the quasi-ordering generated by the transitive and reflexive closure of $\succ \cup \sim$. If there are variables $x, y$ with $x \succ y$ and $y \gtrsim x$, then we say $\gtrsim($ or $\Gamma)$ has cycles, otherwise, it is called cycle-free.

If $\gtrsim$ is cycle-free, then an equivalence class $K$ of $\sim$ is called an SO-cluster. An SO-cluster $K$ is called a top-SO-cluster, iff the variables in $K$ have empty SO-prefix and are maximal w.r.t. $\gtrsim$. The set of equations in $\Gamma$, where the variables from an $S O$-cluster $K$ occur at top-level, is denoted as $E Q(K)$. Let $K_{C}$ be the subset of context variables in $K$. A top-SO-cluster $K$ is called flat, iff it is also $\gtrsim$-minimal.

Note that a non-flat top-SO-cluster may consist of first order variables only. In a decomposed SCUP, a top-SO-cluster always contains a context variable.

### 3.4 Ambiguous SO-cycles

Definition 3.6. (Eliminate ambiguous SO-cycles)
If there is an ambiguous $S O$-cycle with involved $S O$-variables $X_{1}, \ldots, X_{n}$, and amb-depth $d$, then select some $k \in\{1, \ldots, n\}$ and a skeleton context $B$ of depth $\leq(3 * \#(C V)+1) * d$ and replace $X_{k}$ by $B$.

This rule allows to get rid of all ambiguous SO-cycles and also eliminates a context variable from $\Gamma$ after every application.

### 3.5 Expanding Small Powers

If in an expression $\operatorname{pow}(B, n)$, the number $n$ does not exceed $3 * D_{Z}$, then we will expand it with high priority:

Definition 3.7. (expand-small-powers)
$\frac{\{x \doteq \operatorname{pow}(B, n)(y)\} \cup \Gamma}{\{x \doteq t\} \cup \Gamma}$ if $n<3 * D_{Z}$, where $t \equiv \operatorname{expand}(\operatorname{pow}(B, n)(y))$

### 3.6 Path-unique SO-cycles

By decomposition and expansion and By decomposition and expansion of small powers, we can assume, we can assume that a path-unique SO -cycle has no terms of the form $\operatorname{pow}(B, n)(x)$ and no equations of the form $x \doteq y$.

A path-unique SO-cycle is usually written as $s_{1} \doteq C_{1}\left[t_{1}\right], \ldots, s_{n} \doteq C_{n}\left[t_{n}\right]$ where the top-variable of $s_{i}$ occurs in $t_{i-1 \text { mod } n}$. A plateau $P$ is every sequence of equations $s_{j} \doteq C_{j}\left[t_{j}\right], \ldots, s_{j^{\prime}} \doteq C_{j^{\prime}}\left[t_{j^{\prime}}\right]$, such that for $i=j, j+1, \ldots, j^{\prime}-$ $1(\bmod * n), C_{i}=I d$, but $C_{j^{\prime}} \neq I d$, and $C_{j-1 \bmod * n} \neq I d$.

The intuition of this rule is that an instantiation along the cycle is guessed, where the number of rounds is the exponent of periodicity. One distinction is that either some context variable is exhausted, or there is some deviation of a main path from the cycle.

Definition 3.8. Given a path-unique SO-cycle with a minimal number of involved context variables, $s_{1} \doteq C_{1}\left[t_{1}\right], \ldots, s_{n} \doteq C_{n}\left[t_{n}\right]$. First select a plateau in the SO-cycle. For simplicity we assume that the SO-cycle is then renumbered such that it starts with index 1. Now we can use a different method of indexing: Let the $S O$-cycle be $s_{1} \doteq t_{1}, \ldots s_{j_{1}} \doteq C_{j_{1}}\left[t_{j_{1}}\right], \ldots s_{j_{n}} \doteq C_{j_{n}}\left[t_{j_{n}}\right]$, where $C_{j_{i}}$ is the last context in the $i^{\text {th }}$ plateau. Denote the top context variables in plateau $i$ as $X_{i, j}$.

Select an integer $D_{Z} \leq e \leq E_{I} * D_{Z}$, and then select one of the following possibilities:

1. Let $B$ be a skeleton context with $|B| \leq D_{Z}$ and instantiate some $X_{i, j}$ with $B$.
2.     - for $i>1:$ Replace $X_{i, h}$ by pow $\left(C_{j_{i}} C_{j_{i+1}} \ldots C_{j_{i+n \text { mod* }},}, e-i+1\right)\left(X_{i, h}^{\prime}\right)$

- for $i=1:$ For every $h$ replace $X_{1, h}$ either by pow $\left(C_{j_{1}} C_{j_{2}} \ldots C_{j_{n}}, e\right)\left(X_{1, h}^{\prime}\right)$ or by pow $\left(C_{j_{1}} C_{j_{2}} \ldots C_{j_{n}}, e\right)(I d)$, where the last case should be selected at least once.

3. Fail, if the $S O$-cycle has length 1.

- for $i>1$ : Replace $X_{i, h}$ by pow $\left(C_{j_{i}} C_{j_{i+1}} \ldots C_{j_{i+n \text { mod* }},}, e-i+1\right)\left(X_{i, h}^{\prime}\right)$
- for $i=1:$ Let $C_{j_{1}} \equiv f(x_{j_{1}, 1}, \ldots, \underbrace{C_{j_{1}}^{\prime}}_{k_{0}}, \ldots, x_{j_{1}, m})$. For ev-
ery $h$ select an index $1 \leq k_{h} \leq m$ and replace $X_{1, h} \rightarrow$ $\operatorname{pow}\left(C_{j_{1}} C_{j_{2}} \ldots C_{j_{n}}, e\right) f(y_{h, 1}, \ldots, \underbrace{X_{1, h}^{\prime}}_{k_{h}}, \ldots, y_{h, m})$. There should be at least one $k_{h}$ that is different from $k_{0}$. After the replacement, a flattening is performed.

We assume that the new introduced variables are fresh ones.

### 3.7 Flat SO-Clusters

The assumption is that $\Gamma$ is flattened, decomposed, disequation-complete and there are no SO-cycles. Note that every flat top-SO-cluster contains a context variable.

Definition 3.9. Let there be a flat top SO-cluster $K$ with $K_{C}=\left\{X_{1}, \ldots, X_{h}\right\}$ of minimal size in $\Gamma$ with set of equations $E Q(K)$. Fail, if $h=1$ or the maximal arity of function symbols in $\Sigma$ is $\leq 1$.
Let $F$ be a new function symbol with $2 \leq \operatorname{ar}(F) \leq|K|$.
For every context variable $X_{i} \in K$, select an index $1 \leq k_{i} \leq a r(F)$ and replace $X_{i}(\cdot)$ by $F(x_{i, 1}, \ldots, \underbrace{X_{i}^{\prime}(\cdot)}_{k_{i}}, \ldots, x_{i, a r(F)})$, where $x_{i, j}, X_{i}^{\prime}$ are new. There should be different indices $k_{i}$.

Then decompose the equations that result from instantiating and flattening the equations in $E Q(K)$.

Note that the symbol $F$ disappears after decomposition, and that the only possible exit from the iterated application is to remove a context variable.

### 3.8 Non-Flat SO-clusters

This subsection treats the harder case of non-flat SO-clusters.
The assumption is that $\Gamma$ is flattened, decomposed, disequation-complete, and there are no flat top-SO-clusters nor SO-cycles.

Definition 3.10. Let $B \operatorname{DEC}\left(B_{1}, B_{2}\right)$ be the following algorithm applied to two skeleton contexts $B_{1}, B_{2}$ : It signals either Fail, or returns a set of equations between variables:
$B D E C\left(B_{1}, B_{2}\right)$ returns Fail if $\left|B_{1}\right| \neq\left|B_{2}\right| . \quad B D E C(I d, I d)=\emptyset$. $B D E C\left(f\left(x_{1}, \ldots, x_{j_{1}-1}, \cdot, x_{j_{1}+1}, \ldots, x_{n}\right) B_{1}^{\prime}, g\left(y_{1}, \ldots, y_{j_{2}-1}, \cdot, y_{j_{2}+1}, \ldots, y_{m}\right) B_{2}^{\prime}\right)$ results in: if $j_{1} \neq j_{2}$ or $f \neq g$, then Fail, else $\left\{x_{i} \doteq y_{i} \mid i \neq j_{1}\right\} \cup B D E C\left(B_{1}^{\prime}, B_{2}^{\prime}\right)$.

Note that the output of $B D E C$ is always a set of equations between variables, and thus the addition of the equations always makes the SCUP smaller after application of decomposition rules.
Definition 3.11. (power-decomp). This rule is only used after an application of the rule (non-flat-SO-Cluster), and only for the equations in $E Q(K)$ of the non-flat top-SO-cluster after instantiations.

There are four cases for a decomposition of terms starting with a power expression. We assume that after each rule, a flattening is performed if necessary.

1. $\frac{\left\{x \doteq \operatorname{pow}\left(B_{1}, n_{1}\right)\left(x_{1}\right), x \doteq \operatorname{pow}\left(B_{2}, n_{2}\right)\left(x_{2}\right)\right\} \cup \Gamma}{\left\{x \doteq \operatorname{pow}\left(B_{1}, n_{1}\right)\left(x_{1}\right), x \doteq \operatorname{pow}\left(B_{2}, n_{2}\right)\left(x_{2}\right)\right\} \cup B D E C\left(C_{1}, C_{2}\right) \cup \Gamma}$

If $n_{i} \geq 3 * D_{Z}, i=1,2$ and $B_{1} \not \equiv B_{2}$, where $C_{i} \equiv \operatorname{expand}\left(p o w\left(B_{i}, 2 *\right.\right.$ $\left.D_{Z}\right), i=1,2$.
2. $\frac{\left\{x \doteq \operatorname{pow}\left(B_{1}, n_{1}\right)(z), x \doteq f\left(x_{1}, \ldots, x_{n}\right)\right\} \cup \Gamma}{\left\{x_{i} \doteq y_{i} \mid i \neq k\right\} \cup\left\{\operatorname{pow}\left(B_{1}^{\prime}, n_{1}-1\right)(z) \doteq x_{k}\right\} \cup\left\{x \doteq f\left(x_{1}, \ldots, x_{n}\right)\right\} \cup \Gamma}$
where $B_{2}:=\operatorname{shift}\left(B_{1}, 1\right)$, and $f\left(y_{1}, \ldots, y_{k-1}, \cdot, y_{k+1}, \ldots, y_{n}\right)$ is the first atomic context of $B_{1}$.
3. $\frac{\left\{x \doteq \operatorname{pow}\left(B_{1}, n_{1}\right)(z), x \doteq f\left(x_{1}, \ldots, x_{n}\right)\right\} \cup \Gamma}{\text { Fail }}$
if $f \neq \operatorname{head}\left(\operatorname{pow}\left(B_{1}, n_{1}\right)(z)\right)$.
4. $\frac{\left\{x \doteq \operatorname{pow}\left(B, n_{1}\right)\left(x_{1}\right), x \doteq \operatorname{pow}\left(B, n_{2}\right)\left(x_{2}\right)\right\} \cup \Gamma}{\left\{x \doteq \operatorname{pow}\left(B, n_{1}\right)\left(x_{1}\right), x_{1} \doteq \operatorname{pow}\left(B, n_{2}-n_{1}\right)\left(x_{2}\right)\right\} \cup \Gamma} \quad$ if $n_{2} \geq n_{1}$.

In order to give some intuition of the cases in the rule for non-flat SO-cluster, the distinction for the context variables $\left\{X_{1}, \ldots, X_{h}\right\}$ in an SO-cluster is made on the basis of the relative position and depth of the holes of the instances of $X_{i}$. In the case where every non-variable equation in $E Q(K)$ has a power expression at the top, there are the cases i) that some $\sigma\left(X_{i}\right)$ has a small main depth, ii) that some $\sigma\left(X_{i}\right)$ is a prefix of all others and also covered by the power expressions, or iii) that the common prefix of the $\sigma\left(X_{i}\right)$ is long, such that we can decompose, or iv) that the common prefix is long enough, but the bases are already equal, but there is a forking of the instances of $X_{i}$.

Definition 3.12. Rule (non-flat-SO-Cluster)
This rule is only applicable if there are no $S O$-cycles, no flat top-SO-clusters, but a non-flat top-SO-cluster.
Let $K=\left\{X_{1}, \ldots, X_{h}\right\}$ be the context variables in a non-flat top-SO-cluster, where $h$ is minimal.
Then select one of the following two possibilities:

1. If there is an equation $s \doteq f\left(t_{1}, \ldots, t_{n}\right) \in E Q(K)$. Then:

- If there is a further equation $x \doteq t \in E Q(K)$, and $t$ is not of the form $Y(y)$ and head $(t)=g \neq f$, then Fail.
- For every $i=1, \ldots, h$, select an index $k_{i}$ and replace every $X_{i} \in K$ by $f(x_{i, 1}, \ldots, \underbrace{X_{i}^{\prime}(\cdot)}_{k_{i}}, \ldots, x_{i, n})$ where $x_{i, j}, X_{i}^{\prime}$ are new variables.

2. If there is no equation $s \dot{\doteq} f\left(t_{1}, \ldots, t_{n}\right) \in E Q(K)$, but there are at least two equations $x_{1} \doteq \operatorname{pow}\left(B_{1}, n_{1}\right)\left(y_{1}\right), x_{2} \doteq \operatorname{pow}\left(B_{2}, n_{2}\right)\left(y_{2}\right)$ in $E Q(K)$ for different $B_{1}, B_{2}$. Let $\bar{n}$ be the minimum of the numbers $n_{i}$ for all equations $x \doteq \operatorname{pow}\left(B_{i}, n_{i}\right)\left(x_{i}\right)$ in $E Q(K)$. Note that we can assume that $\bar{n} \geq 3 * D_{Z}$. Then select one of the following:

- Select some $m$ with $1 \leq m \leq 3 * D_{Z}$ and replace every $X_{i}$ by pow $\left(B_{1}, m\right)\left(X_{i}^{\prime}\right)$ or by pow $\left(B_{1}, m\right)(I d)$ where the last case should be selected at least once.
- Select a number $0 \leq n \leq 2 * D_{Z}-1$. Let $C_{1}=\operatorname{shift}\left(B_{1}, n\right), f:=$ head $\left(C_{1}\right)$ and the hole of $C_{1}$ in direction $k_{0}$. Fail if $\operatorname{ar}(f) \leq 1$. For every $1 \leq i \leq h$ select an index $1 \leq k_{i} \leq \operatorname{ar}(f)$. Replace every $X_{i}$ by $\operatorname{pow}\left(B_{1}, n\right)(f(x_{i, 1}, \ldots, \underbrace{X_{i}^{\prime}}_{k_{i}}, \ldots, x_{i, a r(f)}))$, where for at least one in-
dex $j: k_{0} \neq k_{j}$. For a fixed equation $x_{0} \doteq \operatorname{pow}\left(B_{0}, n_{0}\right)\left(y_{0}\right) \in E Q(K)$ and every other equation $x_{1} \doteq \operatorname{pow}\left(B_{1}, n_{1}\right)\left(y_{1}\right) \in E Q(K)$ perform $B D E C\left(\operatorname{pow}\left(B_{0}, n\right)\right.$, pow $\left.\left(B_{1}, n\right)\right)$ and add the resulting equations to $\Gamma$.
- For a fixed equation $x_{0} \doteq \operatorname{pow}\left(B_{0}, n_{0}\right)\left(y_{0}\right) \in E Q(K)$ and every other equation $x_{1} \dot{=} \operatorname{pow}\left(B_{1}, n_{1}\right)\left(y_{1}\right) \in E Q(K)$ perform $B D E C\left(p o w\left(B_{0}, 2 *\right.\right.$ $\left.D_{Z}\right)$, pow $\left(B_{1}, 2 * D_{Z}\right)$ ) and add the resulting equations to $\Gamma$.

3. If there is no equation $s \dot{\doteq}\left(t_{1}, \ldots, t_{n}\right) \in E Q(K)$, and for every pair of equations $x_{1} \doteq \operatorname{pow}\left(B_{1}, n_{1}\right)\left(y_{1}\right), x_{2} \doteq \operatorname{pow}\left(B_{2}, n_{2}\right)\left(y_{2}\right)$ it is $B_{1} \equiv B_{2}$. Let $B:=B_{1}$
Let $\bar{n}$ be the minimum of the numbers $n_{i}$ for all equations $x \doteq \operatorname{pow}\left(B, n_{i}\right)\left(x_{i}\right)$ in $E Q(K)$. Note that we can assume that $\bar{n} \geq 3 * D_{Z}$. Then select a number $1 \leq n \leq \bar{n}$ and select one of the following:

- Replace every $X_{i}$ by pow $(B, n)\left(X_{i}^{\prime}\right)$ or by pow $(B, n)(I d)$, where the last case should be selected at least once.
- Replace every $X_{i}$ by pow $(B, \bar{n})\left(X_{i}^{\prime}\right)$.
- Fail if $n=\bar{n}$. Let $C_{1}:=\operatorname{shift}\left(B_{1}, n\right)$, head $\left(C_{1}\right)=f$ and the hole of $C_{1}$ in direction $k_{0}$. Fail if $\operatorname{ar}(f) \leq 1$. For every $1 \leq$ $i \leq h$ select an index $1 \leq k_{i} \leq \operatorname{ar}(f)$. Replace every $X_{i}$ by $\operatorname{pow}(B, n)(f(x_{i, 1}, \ldots, \underbrace{X_{i}^{\prime}}_{k_{i}}, \ldots, x_{i, a r(f)}))$, where at least one index $k_{i}$ must be different from $k_{0}$.

After every replacement, flatten, decompose and power-decompose the resulting equations.

Note that the number $D_{Z}$ is used as a known upper bound for the length of bases after normalization. If the $n$ in the power expressions $\operatorname{pow}(B, n)$ is larger than $2 D_{Z}$, then we are sure that there are at least 2 periods.

### 3.9 How the rules work together: SCUA

The algorithm SCUA has as input a stratified context unification problem $\Gamma$ consisting only of equations between terms. The following steps are performed.

First, the system is flattened in order to exploit sharing.
Then the following rules are applied until the system is empty, or a Fail is signalled, where between rule applications: decomposition rules, powerdecomposition rules, flattening and normalization of power expressions is done with high priority.

1. If there is an ambiguous SO-cycle, then apply the instantiation in 3.4.
2. If there is no ambiguous SO-cycle, but a path-unique SO-cycle, then apply the rule in 3.6 to $\Gamma$.
3. If there are no SO-cycles, and a flat top-SO-cluster, then apply the rule 3.9 for flat top-SO clusters to a minimal one.
4. If there are no SO-cycles, no flat top-SO-clusters, then apply the rule 3.12 to a non-flat top-SO-cluster.

### 3.10 Upper Bounds on the Depth of Instances of Ambiguous SO-Cycles

Theorem 3.13. Let $\Gamma$ be a stratified context unification problem. Let $\Gamma^{\prime}$ be reached by transformations from $\Gamma$, such that $\Gamma^{\prime}$ is solvable by $\sigma$. Let there be an ambiguous $S O$-cycle that can be represented as the unflattened sequence of equations: $X_{1}(\cdot) \doteq C_{1}\left[X_{2}(\cdot)\right], \ldots, X_{m-1}(\cdot) \doteq C_{m-1}\left[X_{m}(\cdot)\right], X_{m}(\cdot) \doteq$ $C_{m}\left[X_{1}(\cdot), X_{1}(\cdot)\right]$. Let d be the sum of $m d t\left(C_{i}\right)$ for $i=1, \ldots, m$ plus the maximum of the depths of the two holes in $C_{1}[\cdot, \cdot]$.

Then there is some context variable $X_{i}$, such that $\sigma\left(X_{i}\right)$ has main depth less than $(3 * m+1) * d$,

The proof is given in the appendix.

## 4 Correctness and Complexity of SCUA

Given the methods in [SS99b], it is a straightforward to adapt the soundness and completeness proofs though it is tedious. The following holds for SCUA: the stratifiedness property is not destroyed by the rules. Furthermore, the number of occurrences of context variables is not increased.

A fact concerning periods in words is used for the completeness of decomposing powers and also for the completeness of solving no-flat top-SO-clusters:

Lemma 4.1. Let $w_{i}, w_{i}^{\prime}$ be words over an alphabet. If $w_{1}^{n} w_{1}^{\prime}=w_{2}^{m} w_{2}^{\prime}$, and $n, m \geq 2$, and $w_{i}^{\prime}$ is a prefix of $w_{i}$, then $w_{i}=w_{3}^{n_{i}}, i=1,2$ for some $n_{i}$ and $w_{3}$.

Lemma 4.2. Let $\sigma\left(\operatorname{pow}\left(B_{1}, n_{1}\right)\left(x_{1}\right)\right)=\sigma\left(\operatorname{pow}\left(B_{2}, n_{2}\right)\left(x_{2}\right)\right)$ and $n_{i} \geq 3 *\left|B_{j}\right|$ for $i, j=1,2$. Then $\sigma\left(\operatorname{pow}\left(B_{1}, n_{1}\right)\right)$ is a prefix of $\sigma\left(\operatorname{pow}\left(B_{2}, n_{2}\right)\right)$ or vice versa.

Proof. Using similar methods as in [SS99b] it is easy to see that if the paths deviate at a position of depth $\leq \max \left(2\left|B_{1}\right|, 2\left|B_{2}\right|\right)$, then there is an occurcheck failure. Then the fact on overlapping periods shows that the two power expressions are both powers of the same skeleton context, hence they have the same main path, and cannot deviate at larger depths.

Another easy to establish fact is that a solvable context unification problem has a solution, where the maximal arity of function symbols is $D_{A}:=$ $\max (2, \operatorname{ar}(f))$, where $f$ is a symbol in $\Gamma_{I}$.

Now we estimate the complexity of the algorithm:
Lemma 4.3. SCUA can be performed in time polynomial in the size and the maximal depths of $S O$-cycles.

Proof. We only argue on the complexity of the critical operations, and assume that the arity of function symbols is $O(n)$. This covers the case of an infinite signature.

First we estimate the number of applications and the size increase by the essential rules:

- The maximal number of applications of eliminating ambiguous SO-cycles is \#CV.
- The maximal number of applications of eliminating SO-cycles is \#CV ${ }^{2}$ : The length of an SO-cycle is at most $\# C V$, and in every application, either the SO-cycle gets shorter, or a context variable is removed.

Now we explore the space increase:
The decomposition rules do not increase space usage. The same holds for the rules for top-SO-clusters, if the subsequent high priority rule applications are taken into account. Every SO-cycle-rule application may add power expressions, but at most $\# C V$. Every power expression may generate $3 * D_{Z}$ occurrences of function symbols. Since the number of applications is $O\left(n^{2}\right)$, the size, and hence the number of function symbols is at most $D_{I}+\# C V^{2} * 3 * D_{A} * D_{Z}$, which is of order $O\left(D_{I}^{3} * D_{Z}\right)$.

The number of introduced power expressions is polynomial in $D_{I}$, since only solving cycles can introduce new ones. The rules for flat clusters may copy some power expressions, however these are removed again after decomposition, power-decomposition, and normalization. For simplicity, the resource requirement for expansions of power expressions are counted as contribution of the cycle-elimination rules.
Third we estimate the number of applications of the SO-cluster rules:

- The maximal number of applications of eliminating a flat top-SO-cluster is $\# C V^{2}$ : Every application strictly reduces the number of context variables in a flat top-SO-cluster, or removes a context variable.
- The maximal number of applications of eliminating a non-flat top-SO-cluster is harder to establish. The tuple (number of context variables, number of context variables in the top-SO-cluster, number of variables not in any top-SO-cluster, number of occurrences of function symbols on top level) strictly
decreases lexicographically after every application of the rule for eliminating non-flat top-SO-clusters (including subsequent high priority rules). The last parameter is of order $O\left(D_{I}^{3} * D_{Z}\right)$, the same for the number of variables. The worst case corresponds to multiplication, i.e. the number of applications is smaller than $p\left(D_{I}\right) * D_{Z}^{2}$, where $p$ is some polynomial.

It remains to estimate the contribution of every single rule application together with the following flattening, decomposition etc. It is easy to see that flattening, decomposition, and normalization require time polynomial in the size.

- Instantiating an ambiguous SO-cycle: Is of order $p\left(D_{I}\right) * D_{Z}$, where $p$ is some polynomial.
- Solving path-unique SO-cycles is of order $p\left(D_{I}\right) * D_{Z}$, where $p$ is some polynomial.
- SO-cluster elimination: Eliminating a flat SO-cluster requires comparably less resources.
If it is a non-flat SO-cluster, then the overall usage of time is $p\left(D_{I}\right) * D_{Z}^{2}$.
Corollary 4.4. The time required to perform a non-deterministic run of SCUA is polynomial in the initial size $D_{I}$ and the maximal depth $D_{Z}$ of an SO-cycle.


## 5 Future Work

The complexity of stratified context unification remains an issue. Among others, the paper shows that an upper bound on the depth of SO-cycles implies a complexity estimate of stratified context unification. Proving better complexity estimations of stratified context unification or proving an upper bound for the depth of SO-cycles is left for future work.

The decision algorithm for bounded second order unification [SS99a] is very similar to the decision algorithm for stratified context unification. The methods developed in this paper may be used in an estimation of its complexity.

Perhaps the tools in this paper help in computing an upper bound for the complexity of D-unification [SS98], however, this would require a careful inspection of the algorithm since context unification is not used as a module.

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## Appendix

## A Proof of Theorem 3.13

The main purpose of this section is to show that in an ambiguous SO-cycle there exists at least one context variable that has an instance of a main depth $O(n * d)$, where $n$ is the number of context variables in the cycle and $d$ is the amb-depth of the SO-cycle.

In this section we only compute in instantiated terms and contexts: Hence in this section the variables $X, Y$ denote contexts, so we can speak of their main depth and their size.

An SO-cycle is a chain of equalities $X_{i}\left(s_{i}\right)=r_{i}, \mathrm{i}=1, \ldots, \mathrm{n}$, such that $X_{i}$ is contained in $r_{i-1 \text { mod* } n}$, and such that at least one occurrence in $r_{i}$ is not at the top. The length of the SO-cycle is $n$, i.e., the number equations. The depth of the SO-cycle is the maximal sum of the depths of $X_{i}$ in $r_{i-1} \bmod { }_{n}$.

In the following proof, the argument term $t$ in $X(t)$ does not really matter, so we use the notation $X \sim Y$ as abbreviation of an equality $X(s)=Y(t)$. Analogously, we use $X \sim C[Y]$ for $X(s) \sim C[Y[t]]$ and $X \sim C[Y, Z]$ for $X(s) \sim$ $C\left[Y\left[t_{1}\right], Y\left[t_{2}\right]\right]$ where $C$ is a multicontext.

Lemma A.1. Let the following chain of equations be given, $X_{1} \sim \ldots \sim X_{n} \sim$ $C\left[X_{1}, \ldots, X_{1}\right]$ and let $C$ have at least $n+1$ holes and let d be the maximum of the depths of the holes in $C$.

Then for some $i: \operatorname{mdt}\left(X_{i}\right) \leq d$.
Proof. We can assume that $m d t\left(X_{i}\right)>d$ for all $i$.
The proof is by induction on $n$ : If $n=1$, then the lemma holds. Otherwise consider the cases for $X_{n}$.

- $X_{n}$ has all the holes of $C$ in its side area, then the derived chain is $X_{1} \sim$ $\ldots \sim X_{n-1} \sim C^{\prime}\left[X_{1}, \ldots, X_{1}\right]$, where the depths of the holes are the same as in $C$, and we can use induction on $n$.
- Wlog. $X_{n}=C\left[X_{n}^{\prime}, X_{1}(), \ldots, X_{1}()\right]$. Then the obtained chain is $X_{1} \sim \ldots \sim$ $X_{n-1} \sim C\left[X_{n}^{\prime}, X_{1}, \ldots, X_{1}\right]$, and we can use induction.

Lemma A.2. Let the following equations be given:

$$
X_{1} \sim X_{2} \sim \ldots \sim X_{n} \sim C\left[X_{\varphi(n)}, X_{\varphi(n-1)}, \ldots, X_{\varphi(0)}\right]
$$

where $\varphi:[0 . . n] \rightarrow[1 . . n]$ is monotone. A ssume the depth of the holes corresponding to $X_{\varphi(j)}, j=1, \ldots, n$ in $C$ is at most $(n-j+h) * d$. Then for some $i$ : $m d t\left(X_{i}\right) \leq(n-i+h) * d$

Proof. We can assume that the main depths are larger than given in the lemma. If $n=1$, then the lemma holds, since there are two occurrences of $X_{1}$ and the depth is at most $h * d$.

Now let $n>1$. We can assume that $\operatorname{mdt}\left(X_{i}\right)>(n-i+h) * d$.
Consider the possibilities for $X_{n}$.

- If $\varphi(n)=\varphi(n-1)=n$, then there are two occurrences of $X_{n}$ and $m d t\left(X_{n}\right) \leq$ $h * d$.
- If $\varphi(n)=n>\varphi(n-1)$, then only $X_{n}=C\left[X_{n}^{\prime}, X_{\varphi(n-1)}(), \ldots, X_{\varphi(0)}()\right]$ is possible, and the new equation chain is

$$
X_{1} \sim X_{2} \sim \ldots \sim X_{n-1} \sim C\left[X_{n}^{\prime}, X_{\varphi(n-1)}, \ldots, X_{\varphi(0)}\right]
$$

We can ignore $X_{n}^{\prime}$, since $\varphi(n-1) \leq n-1$ and then apply induction on $n$ using $n^{\prime}:=n-1$ and $h^{\prime}:=h+1$.

- If $\varphi(n)>n$, there are two possibilities for $X_{n}$.
- $X_{n}$ has all the holes of $C$ in its side-area, then: $X_{1} \sim X_{2} \sim \ldots \sim X_{n-1} \sim$ $C^{\prime}\left[X_{\varphi(n)}, X_{\varphi(n-1)}, \ldots, X_{\varphi(0)}\right]$, and the holes in $C^{\prime}$ are at the same depth as in $C$. We can use induction on $n$, using $n^{\prime}:=n-1, h^{\prime}:=h, \varphi^{\prime}(j):=$ $\varphi(j+1)$.
- $X_{n}=C[\ldots, \underbrace{X_{n}^{\prime}}_{j}, \ldots]$ : Then the new chain is: $X_{1} \sim X_{2} \sim \ldots \sim X_{n-1} \sim$ $C^{\prime}[X_{\varphi(n)}, \ldots, \underbrace{X_{n}^{\prime}}_{j}, \ldots, \ldots, X_{\varphi(0)}]$
The chain is shortened if the $j^{\text {th }}$ hole is ignored, and we can use induction on $n$ using $n^{\prime}:=n-1$ and $h^{\prime}:=h+1$, and $\varphi^{\prime}(i)=\varphi(i)$ or $\varphi^{\prime}(i)=\varphi(i+1)$. Then $d\left(X_{\varphi^{\prime}(i)}\right)=d\left(X_{\varphi(i \vee i+1)}\right) \leq n-i+h=n^{\prime}-i+h^{\prime}$. The result is $m d t\left(X_{i}\right) \leq\left(n^{\prime}-i+h^{\prime}\right) * d=(n-i+h) * d$.

Lemma A.3. Let $m, k, n, N$ be numbers with $m, n \geq 1, n+1 \geq k, N=m+n$, and let the following equations be given:

$$
\begin{aligned}
& X_{1} \sim \ldots \sim X_{n} \sim D\left[X_{\varphi(k)}, \ldots, X_{\varphi(1)}, Y_{h}\right] \\
& Y_{1} \sim \ldots \sim Y_{m} \sim C\left[Y_{1}, X_{1}\right]
\end{aligned}
$$

where $\varphi:[1 . . k] \rightarrow[1 . . n]$ is monotone, the depths of the holes of $X_{\varphi(j)}$ in $D$ is $\leq(k-j+1) * d$, the depth of $Y_{h}$ is $\leq k * d$, and the depth of $Y_{1}, X_{1}$ in $C$ is $\leq \bar{d}$.

Then one of the following holds:

- for some $X_{i}: \operatorname{mdt}\left(X_{i}\right) \leq(N-i+1) * d$ or
- for some $Y_{i}$ with $i \geq h: \operatorname{mdt}\left(Y_{i}\right) \leq(2 N-k+1) * d$ or
- for some $Y_{i}$ with $i<h: \operatorname{mdt}\left(Y_{i}\right) \leq(2 N-k) * d$.

Proof. If $n+1=k$, then we can use Lemma A.2, which shows that for some $i$ : $m d t\left(X_{i}\right) \leq n-i+1$. Hence in the following we can assume that $n \geq k$.

The proof is by induction on the following parameters: the number $m$, then $m-h$, then $n-k$.
Base case: $m=1$. Then $Y_{1} \sim C\left[Y_{1}, X_{1}\right]$ implies that $Y_{1}$ has $X_{1}$ in its side area at least $N-k$ times, where the depths are: $d, \ldots,(N-k) * d$. Using an appropriate $\varphi$, Lemma A. 2 implies that some $m d t\left(X_{i}\right) \leq(N-i+1) * d$.

## Induction:

case $h<m$ : We distinguish the cases for $Y_{m}$ in the equation $Y_{m} \sim C\left[Y_{1}, X_{1}\right]$. There are three cases:

- $Y_{m}$ has the holes of $C$ in its side area, i.e. $X_{1}, Y_{1}$ are in the side area. Then

$$
\begin{aligned}
& X_{1} \sim \ldots \sim X_{n} \sim D\left[X_{\varphi(k)}, \ldots, X_{\varphi(1)}, Y_{h}\right] \\
& Y_{1} \sim \ldots \sim Y_{m-1} \sim C^{\prime}\left[Y_{1}, X_{1}\right]
\end{aligned}
$$

where the depths in $C^{\prime}$ are the same. We can use induction on $m$.
$-Y_{m}=C\left[Y_{m}^{\prime}, X_{1}()\right]$. Then

$$
\begin{aligned}
& X_{1} \sim \ldots \sim X_{n} \quad \sim D\left[X_{\varphi(k)}, \ldots, X_{\varphi(1)}, Y_{h}\right] \\
& Y_{m}^{\prime} \sim Y_{1} \sim \ldots \sim Y_{m-1} \sim C\left[Y_{m}^{\prime}, X_{1}\right]
\end{aligned}
$$

and by induction on the distance of $m-h$, we get the upper bounds for $m d$. We have to check only $Y_{m}$ : If $m d t\left(Y_{m}^{\prime}\right) \leq(2 N-k) * d$, then $m d t\left(Y_{m}\right) \leq$ $(2 N-k+1) * d$.
$-Y_{m}=C\left[Y_{1}(), Y_{m}^{\prime}\right]$. Then

$$
\begin{aligned}
& Y_{m}^{\prime} \sim X_{1} \sim \ldots \sim X_{n} \sim D\left[X_{\varphi(k)}, \ldots, X_{\varphi(1)}, Y_{h}\right] \\
& Y_{1} \sim \ldots \sim Y_{m-1} \quad \sim C\left[Y_{1}, Y_{m}^{\prime}\right]
\end{aligned}
$$

We use induction on $m$. We have to check only $Y_{m}$ : If $\operatorname{mdt}\left(Y_{m}^{\prime}\right) \leq N$, then $m d t\left(Y_{m}\right) \leq(2 N-k+1) * d$, since $n \geq k$.
case $h=m$ :
The equations are of the form:

$$
\begin{aligned}
& X_{1} \sim \ldots \sim X_{n} \sim D\left[X_{\varphi(k)}, \ldots, X_{\varphi(1)}, Y_{m}\right] \\
& Y_{1} \sim \ldots \sim Y_{m} \sim C\left[Y_{1}, X_{1}\right]
\end{aligned}
$$

A case analysis for $Y_{m}$ using the equations $Y_{m} \sim C\left[Y_{1}, X_{1}\right]$ gives three cases

- $Y_{m}$ has the holes of $C$ in its side area, i.e., $X_{1}, Y_{1}$ are in the side area. Then

$$
\begin{aligned}
& X_{1} \sim \ldots \sim X_{n} \sim D\left[X_{\varphi(k)}, \ldots, X_{\varphi(1)}, C^{\prime}\left[Y_{1}, X_{1}\right]\right] \\
& Y_{1} \sim \ldots \sim Y_{m-1} \sim C^{\prime}\left[Y_{1}, X_{1}\right]
\end{aligned}
$$

We use induction on $m$. Note that $N^{\prime}=N-1, k^{\prime}=k+1$, hence $N-k=$ $N^{\prime}-k^{\prime}$.
$-Y_{m}=C\left[Y_{m}^{\prime}, X_{1}()\right]$. Then

$$
\begin{aligned}
& X_{1} \sim \ldots \sim X_{n} \quad \sim D\left[X_{\varphi(k)}, \ldots, X_{\varphi(1)}, C\left[Y_{m}^{\prime}, X_{1}\right]\right] \\
& Y_{m}^{\prime} \sim Y_{1} \sim \ldots \sim Y_{m-1} \sim C\left[Y_{m}^{\prime}, X_{1}\right]
\end{aligned}
$$

We use induction on $m-h$ : It is $k^{\prime}=k+1: N^{\prime}=N, m^{\prime}=m$. The conditions for $X_{i}$ is the same. We have to check that from the induction hypothesis we can prove the estimations for $Y_{i}$. The estimation is $m d t\left(Y_{i}\right) \leq\left(2 N-k^{\prime}+1\right) * d$ and $m d t\left(Y_{m}^{\prime}\right) \leq\left(2 N-k^{\prime}+1\right) * d$. This implies $m d t\left(Y_{i}\right) \leq(2 N-k) * d$ for $i<m$ and $m d t\left(Y_{m}^{\prime}\right) \leq(2 N-k) * d$, hence $m d t\left(Y_{m}\right) \leq(2 N-k+1) * d$.
$-Y_{m}=C\left[Y_{1}(), Y_{m}^{\prime}\right]$. Then

$$
\begin{aligned}
& Y_{m}^{\prime} \sim X_{1} \sim \ldots \sim X_{n} \sim D\left[X_{\varphi(k)}, \ldots, X_{\varphi(1)}, C\left[Y_{1}, Y_{m}^{\prime}\right]\right] \\
& Y_{1} \sim \ldots \sim Y_{m-1}
\end{aligned}
$$

We use induction on $m$. If $m d t\left(Y_{m}^{\prime}\right) \leq N$, then also $m d t\left(Y_{m}\right) \leq N-k$. It is $k^{\prime}=k+1$, which implies the estimation of $Y_{i}$ as given in the lemma.

Lemma A.4. Let

$$
\begin{aligned}
& X_{1} \sim \ldots \sim \quad X_{j} \sim \ldots \sim X_{n} \sim C\left[Y_{1}, X_{1}\right] \\
& Y_{1} \sim \ldots \sim Y_{m} \sim \quad X_{j}
\end{aligned}
$$

and the depth of the holes in $C$ is less than d. Let $N=n+m$.
Then there is some $X_{i}$ such that $m d t\left(X_{i}\right) \leq(2 N) * d$ for $j<i$ or $m d t\left(X_{i}\right) \leq$ $(2 N+1) * d$ for $i \leq j$ or some $Y_{i}$ with $m d t\left(Y_{i}\right) \leq 2 * N * d$

Proof. If $j=n$, then there are three cases. In every case we can use lemma A. 3 and get a bound of $2 N d$.

In the case $j \neq n$, we use induction on $n+m$ and then on $n-j$.
Case analysis for $X_{n}$ :

- $X_{n}$ may have the holes of $C$ in its side area, then we can use induction on $n$.
$-X_{n}=C\left[X_{n}^{\prime}, X_{1}()\right]$, then the new chains of equations are $X_{1} \sim \ldots \sim X_{j} \sim$ $\ldots \sim X_{n-1} \sim C\left[X_{n}^{\prime}, X_{1}\right]$ and $X_{n}^{\prime} \sim Y_{1} \sim \ldots Y_{m} \sim X_{j}$. Induction on $n-j$ shows the claim.
$-X_{n}=C\left[Y_{1}(), X_{n}^{\prime}\right]$, then the new chains of equations are $X_{n}^{\prime} \sim X_{1} \sim \ldots \sim$ $X_{j} \sim \ldots \sim X_{n-1} \sim C\left[Y_{1}(), X_{n}^{\prime}\right]$ and $Y_{1} \sim \ldots Y_{m} \sim X_{j}$. We can use induction on $n-j$.

Lemma A.5. Let $X_{1} \sim \ldots \sim X_{j} \sim \ldots \sim X_{n} \sim C\left[X_{j}, X_{1}\right]$ and the depth of the holes in $C$ is less than $d$.

Then there is some $X_{i}$ such that $m d t\left(X_{i}\right) \leq(2 N) * d$ for $j<i$ or $m d t\left(X_{i}\right) \leq$ $(2 N+1) * d$ for $i \leq j$.
Proof. Follows easily by considering the possibilities for $X_{n}$ in the same way as already demonstrated using induction and Lemma A. 4

Proposition A.6. Let $X_{1} \sim \ldots \sim X_{n} \sim C\left[X_{1}, X_{1}\right]$, and the depth of the holes in $C$ is less than $d$. Then there is some $X_{i}$ of with $\operatorname{mdt}\left(X_{i}\right) \leq(2 * n+1) * d$

## Proof. Follows from Lemma A. 5

Lemma A.7. Let an ambiguous SO-cycle $X_{1} \sim C_{1}\left[X_{2}\right] \sim \ldots \sim X_{n} \sim$ $C_{n}\left[X_{1}, X_{1}\right]$ be given, let $d_{j}=\operatorname{mdt}\left(C_{j}\right), j=1, \ldots, n-1 ; d_{n}$ be the maximum of the depths of $C_{n}$ and $d=\sum_{i=j}^{n} d_{i}$.

Let $e_{i}=d-\sum_{k=1}^{i} d_{k}$. Then there is some $X_{i}$ with $\operatorname{mdt}\left(X_{i}\right) \leq\left(3 n+1-e_{i}\right) * d$
Proof. Using induction on the torque $\sum_{i=1}^{n-1} i * d_{i}$. If all $d_{i}=0$ for all $i<n$, then Proposition A. 6 shows the claim.

Let $j$ be the first index such that $C_{j}$ is not trivial. We can assume that $j<n$. Consider the possibilities for $X_{j}$ for $j>1$ If $X_{j}$ contains the hole of $C_{j}$ in the side area, then $X_{j-1} \sim C_{j}^{\prime}\left[X_{j+1}\right]$ where $m d t\left(C_{j}^{\prime}\right)=m d t\left(C_{j}\right)$ and induction shows the claim.

If $X_{j}=C_{j}\left[X_{j}^{\prime}\right]$, then the part of the chain is modified to: $\ldots, X_{j-1} \sim$ $C_{j-1} C_{j}\left[X_{j}^{\prime}\right], X_{j}^{\prime} \sim X_{j+1}, \ldots$. Since in the torque $(j-1) * d_{j-1}+j * d_{j}$ is replaced by $(j-1) *\left(d_{j-1}+d_{j}\right)$, we can use induction.

In the cases where $j=1$, the torque is also decreased, however, $C_{n}$ is increased.

Theorem A.8. In an ambiguous SO-cycle $X_{1} \sim C_{1}\left[X_{2}\right], X_{2} \sim$ $C_{2}\left[X_{3}\right], \ldots \ldots X_{n} \sim C_{n}\left[X_{1}, X_{1}\right]$, let $d$ be the sum of the depths of $X_{i+1}$ in $C_{i}$ for $i=1, \ldots, n-1$ plus the maximal depths of the holes in $C_{n}$.

Then there is some $X_{i}$ of main depth less than $(3 * n+1) * d$
Proof. This is a special case of Lemma A.7.
Example A.9. Consider the equation chain $X \sim Y \sim f(X, X, t)$, where we omit the arguments of context variables. Then either $Y=f\left(X, X, Y^{\prime}\right)$, hence $X \sim$ $f\left(X, X, Y^{\prime}\right), X=I d$. If $Y=f\left(Y^{\prime}, X, t\right)$, then $Y^{\prime} \sim X \sim f\left(Y^{\prime}, X, t\right)$, and $X=f\left(Y^{\prime}, f\left(Y^{\prime}, X^{\prime}, t\right), t\right)$. Then $Y^{\prime} \sim f\left(Y^{\prime}, f\left(Y^{\prime}, X^{\prime}, t\right), t\right)$, hence $Y^{\prime}=I d$. This gives a bound of 1 in contrast to 7 as given by Theorem A. 8 .

