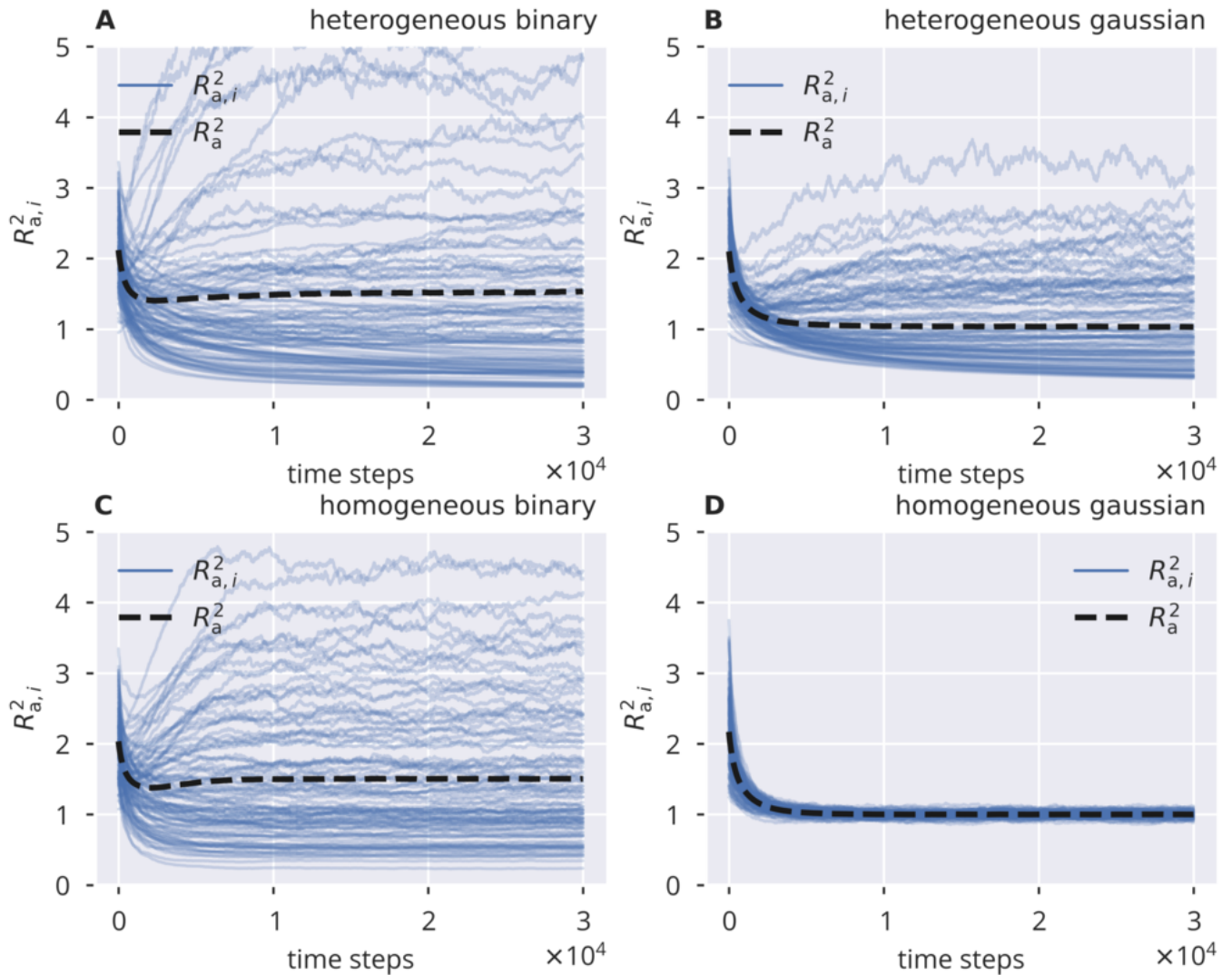
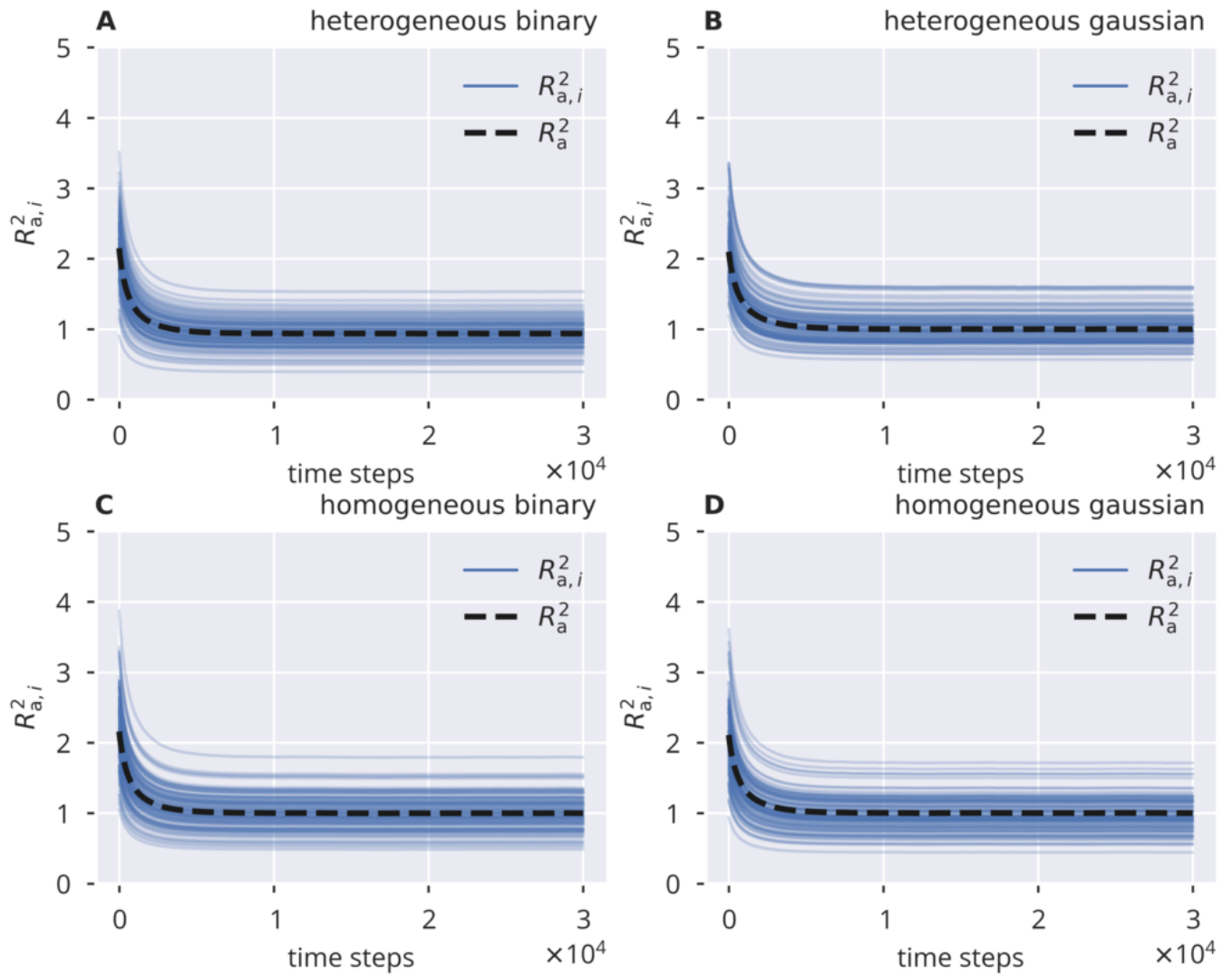


## Supplementary Material

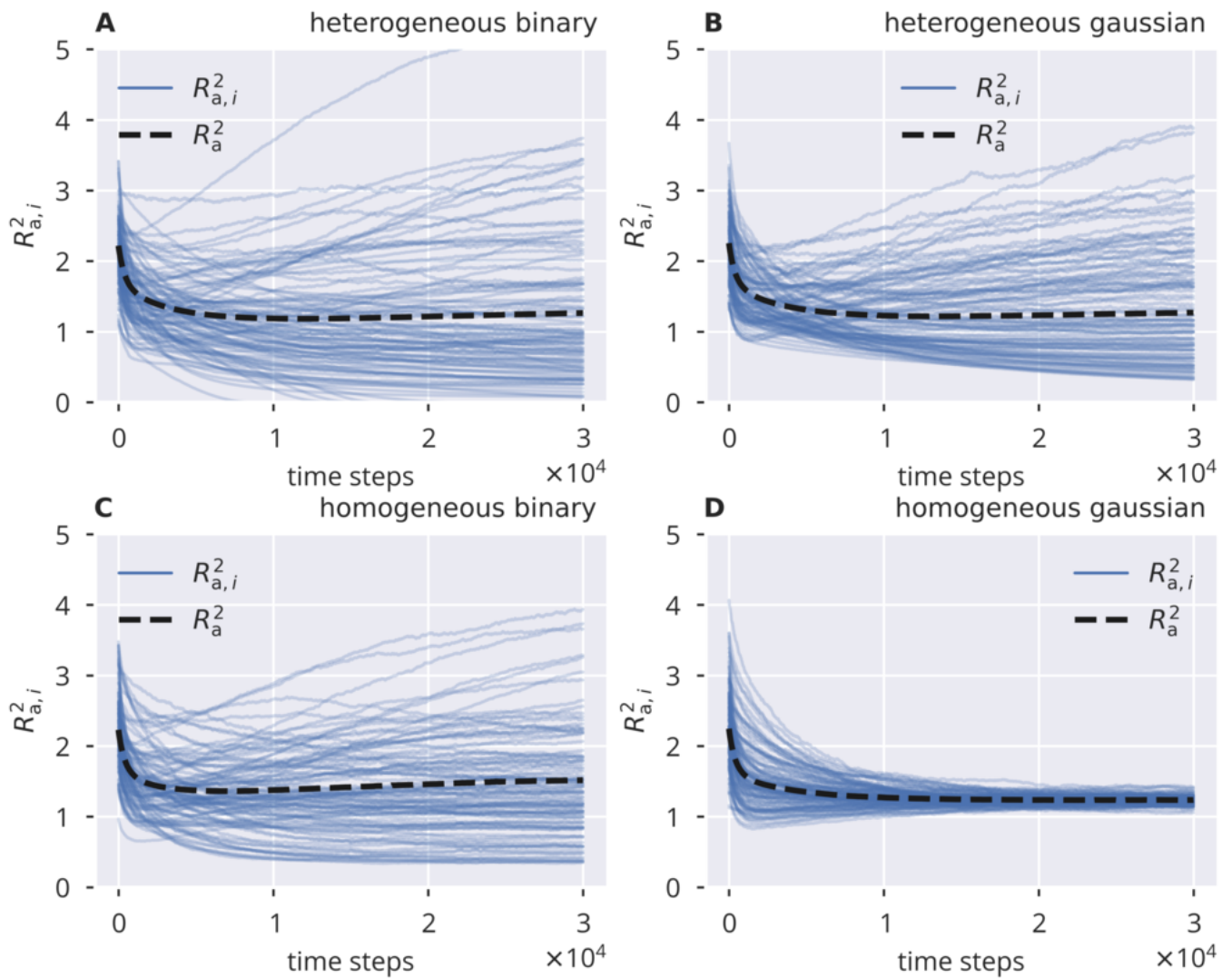
### 1 SUPPLEMENTARY FIGURES



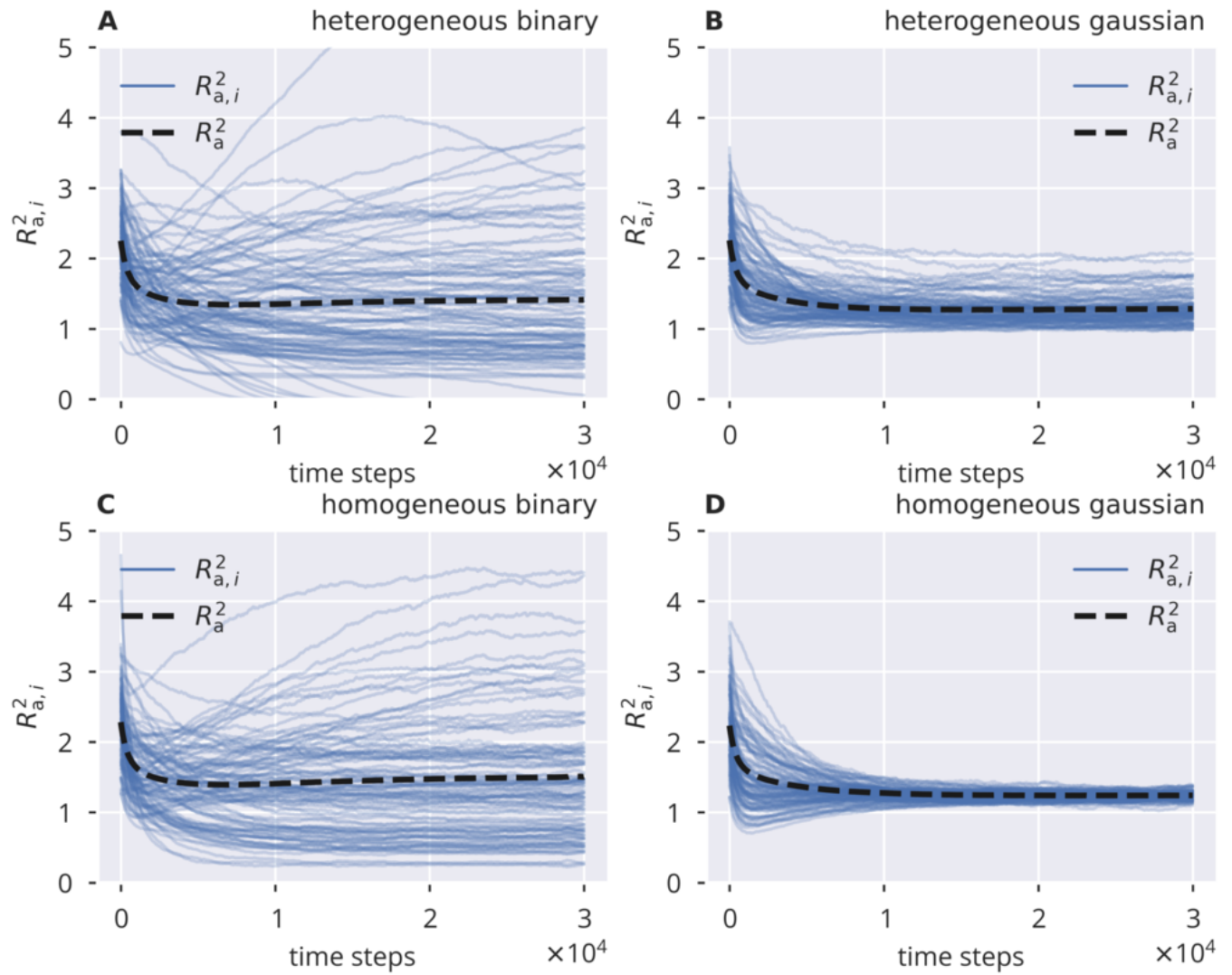
**Figure S1. Adaptation dynamics, flow control, local** Panels A–D show the dynamics of the square spectral radius  $R_a^2$  and local estimates  $R_{a,i}^2$  under local flow control for different input protocols, as given in the panel titles.



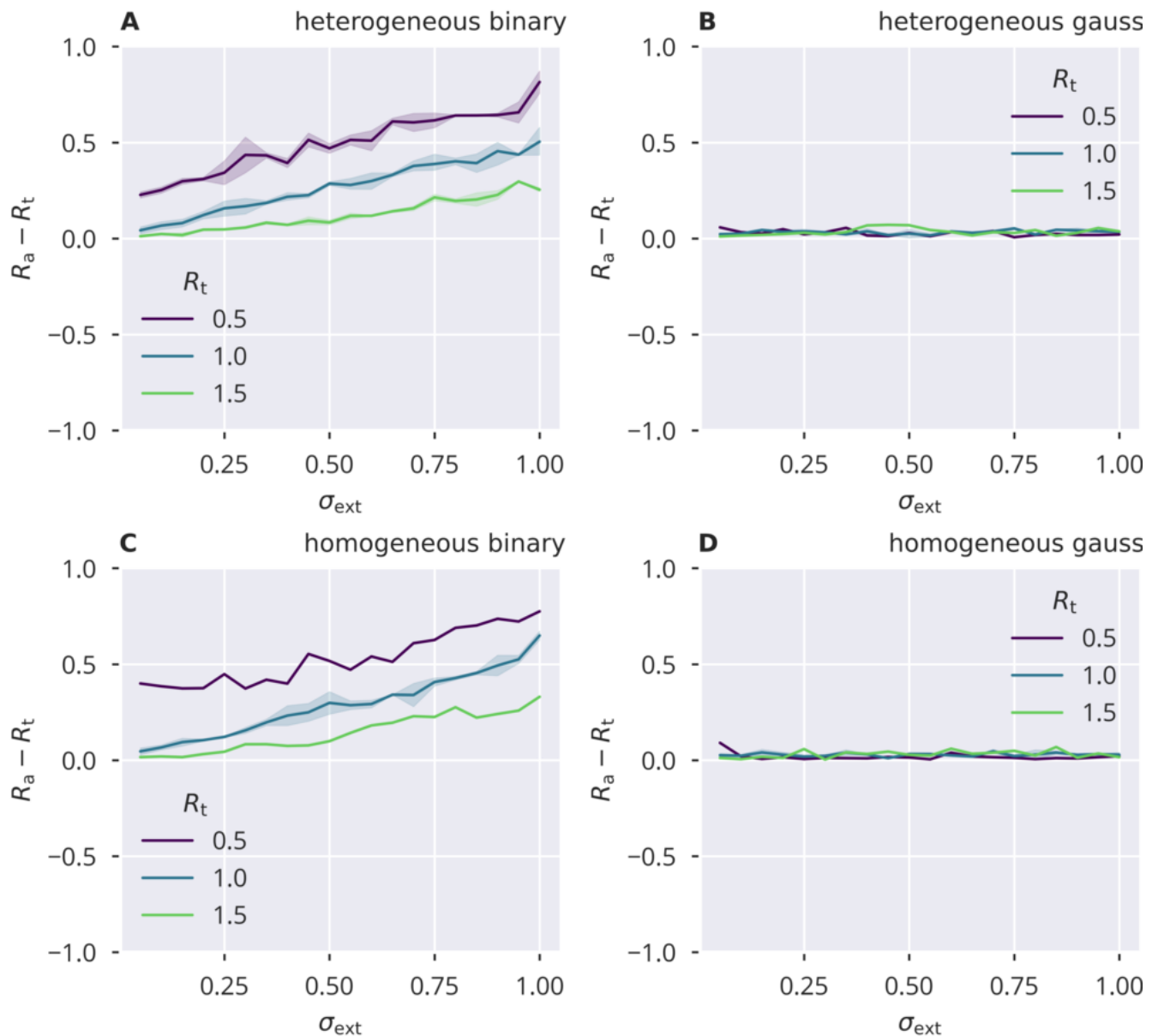
**Figure S2. Adaptation dynamics, flow control, global** Panels A–D show the dynamics of the square spectral radius  $R_a^2$  and local estimates  $R_{a,i}^2$  under global flow control for different input protocols, as given in the panel titles.



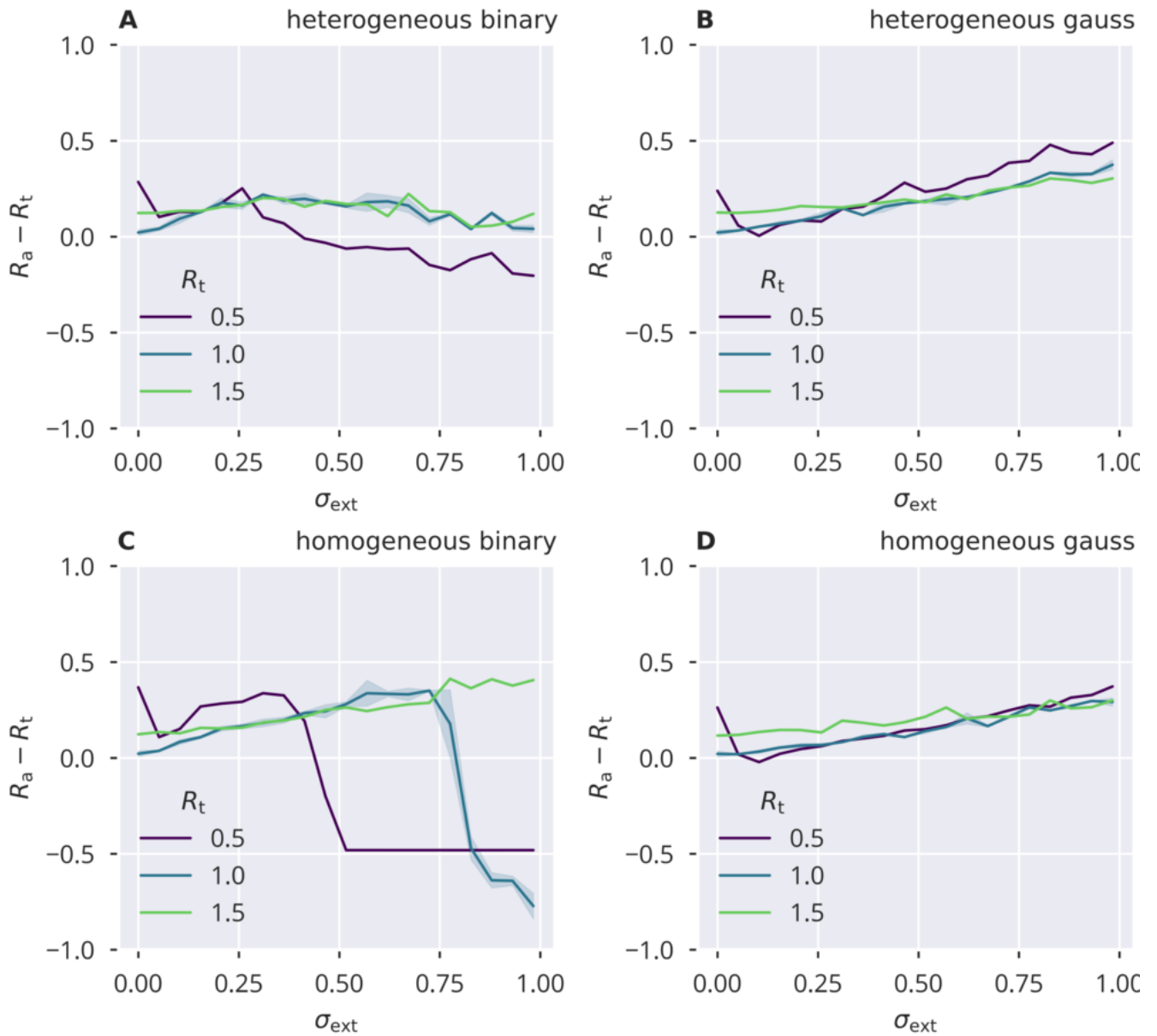
**Figure S3. Adaptation dynamics, variance control, local** Panels A–D show the dynamics of the square spectral radius  $R_a^2$  and local estimates  $R_{a,i}^2$  under local variance control for different input protocols, as given in the panel titles.



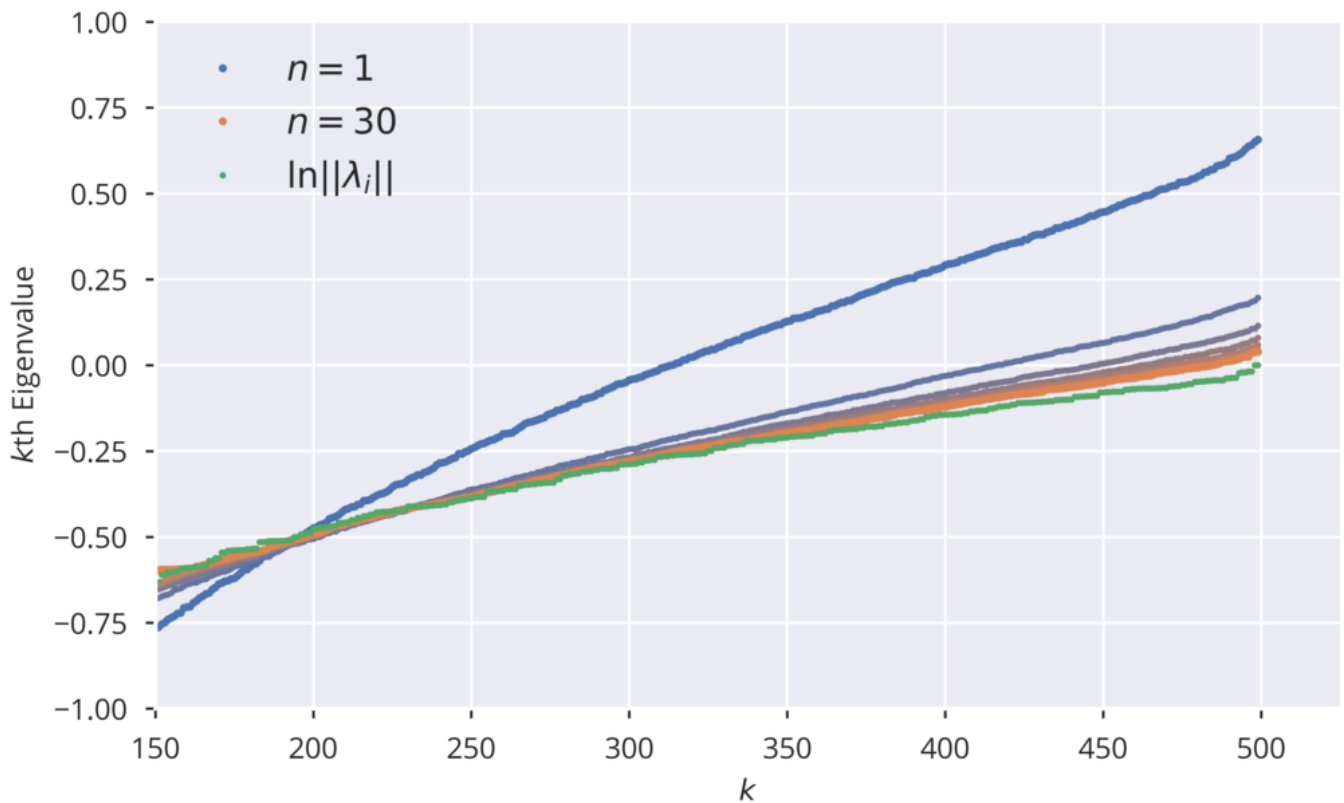
**Figure S4. Adaptation dynamics, variance control, global** Panels A–D show the dynamics of the square spectral radius  $R_a^2$  and local estimates  $R_{a,i}^2$  under global variance control for different input protocols, as given in the panel titles.



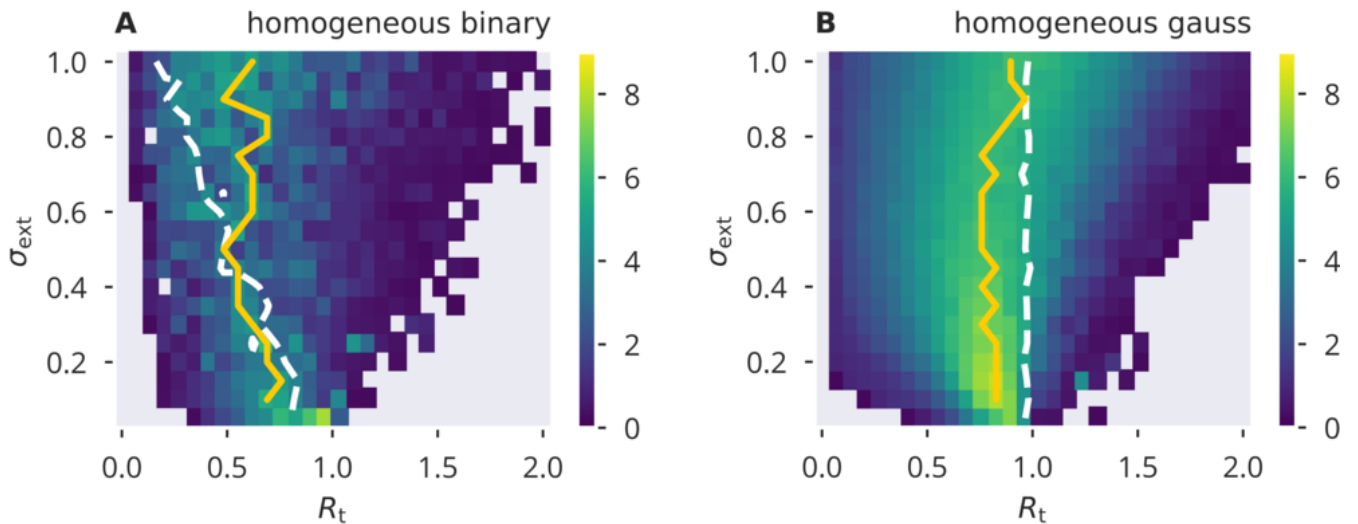
**Figure S5. Difference of the spectral radius after adaptation and the target spectral radius, flow control** For different standard deviations  $\sigma_{\text{ext}}$  of the external input, the error  $R_a - R_t$  between the resulting spectral radius  $R_a$  and the target spectral radius  $R_t$  was determined. Heterogeneous/homogeneous binary input (A/C) led to positive deviations from the target spectral radius for stronger external input. Heterogeneous/homogeneous Gaussian input (B/D) yielded perfect alignment between  $R_a$  and  $R_t$ . Local adaptation was used for both panels.



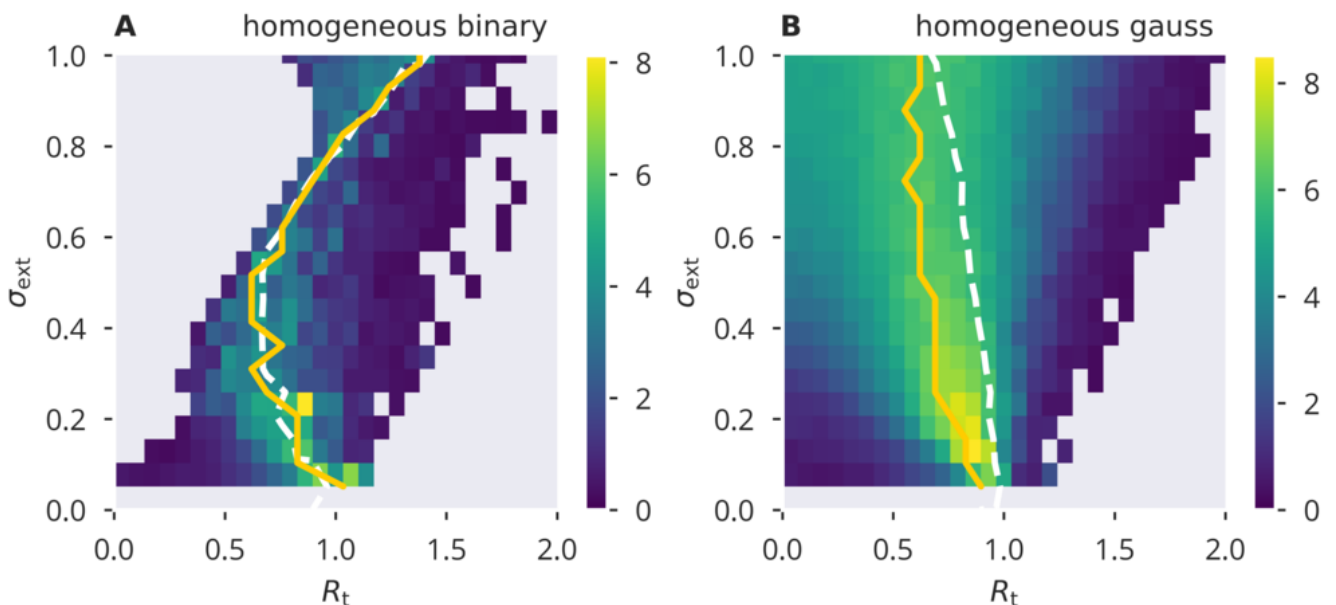
**Figure S6. Difference of the spectral radius after adaptation and the target spectral radius, variance control** For different standard deviations  $\sigma_{\text{ext}}$  of the external input, the error  $R_a - R_t$  between the resulting spectral radius  $R_a$  and the target spectral radius  $R_t$  was determined. Heterogeneous binary input (**A**) led to a good alignment. On the other hand, homogeneous binary input (**C**) caused strong deviation from the target for larger input. Heterogeneous/homogeneous Gaussian input (**B/D**) both resulted in positive deviations that increased for larger input strengths. Local adaptation was used for both panels.



**Figure S7. Convergence of Lyapunov Spectrum.** Convergence of eigenvalues of  $\ln \left( (\widehat{W}^n)^\dagger \widehat{W}^n \right) / (2n)$  for different  $n$ , as discussed in Section 2.6.  $\widehat{W}$  is a random Gaussian matrix which was rescaled to a spectral radius of one. Colors from blue to orange encode the exponent  $n$  ranging between 1 and 30. Green dots show the theoretical limit of  $\ln \|\lambda_i\|$ , where  $\lambda_i$  is the  $i$ th eigenvalue of  $\widehat{W}$ .

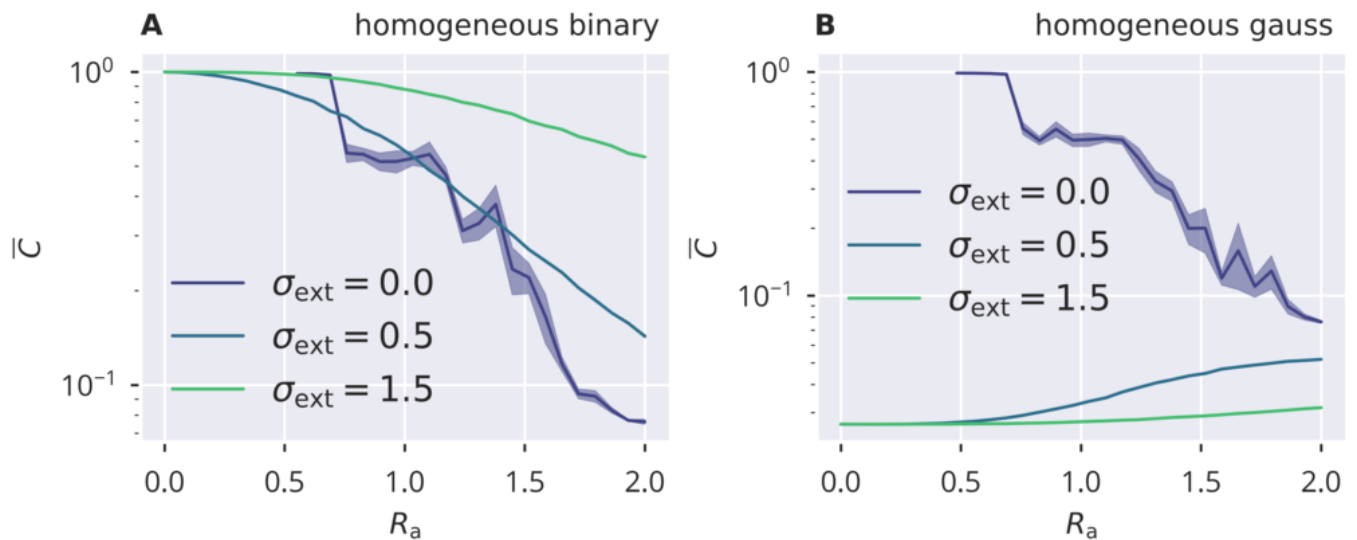


**Figure S8. XOR performance for flow control, homogeneous input.** Numerical results for the network performance under a time-delayed XOR task, as defined in Section 2.7, using homogeneous binary/Gaussian input. Shown are color-coded performance sweeps for the XOR-performance (18), averaged over five trials. The input has variance  $\sigma_{\text{ext}}^2$  and the target for the spectral radius  $R_t$ . A/B panels are for binary/Gaussian input protocols. Optimal performance for a given  $\sigma_{\text{ext}}$  is given by yellow solid lines, measured value of  $R_a = 1$  by white dashed lines.

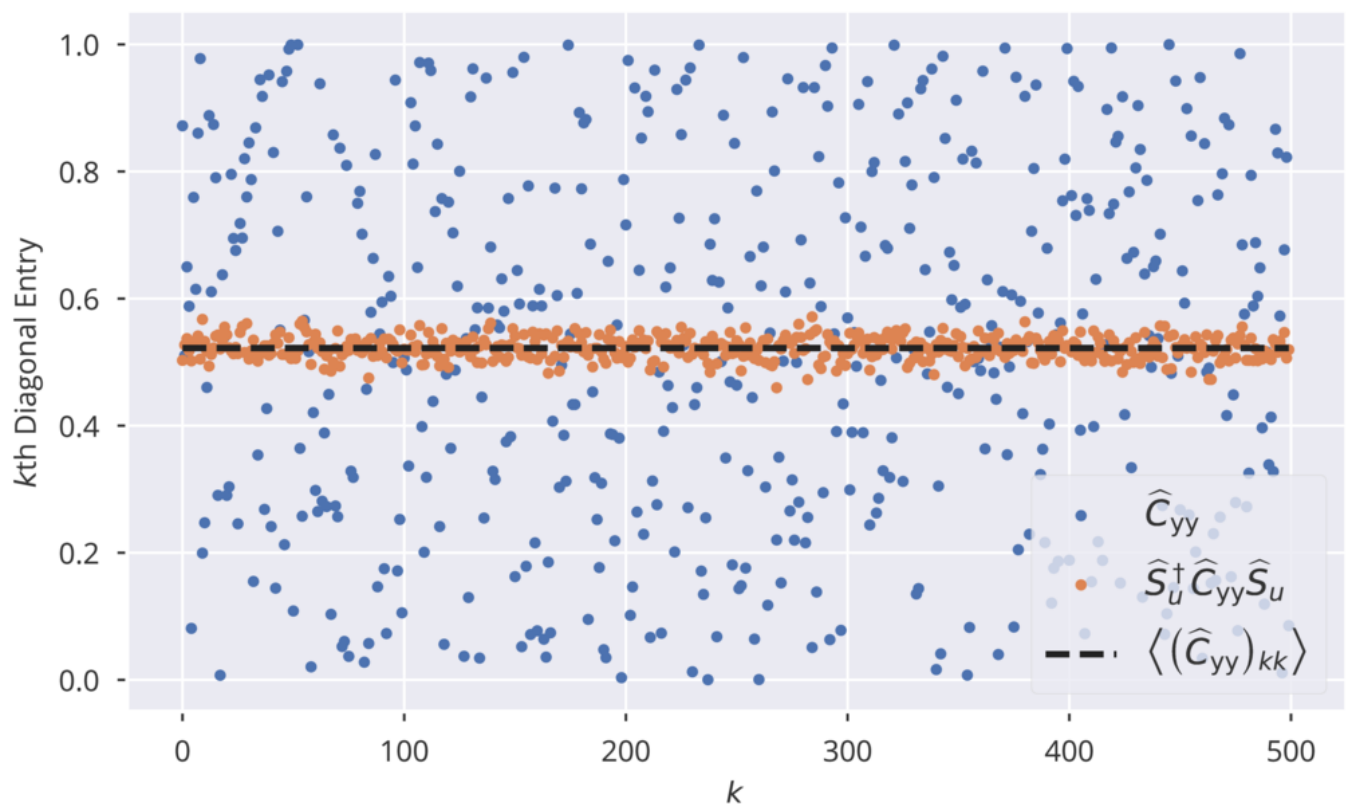


**Figure S9. XOR performance for variance control, homogeneous input.** Numerical results for the network performance under a time-delayed XOR task, as defined in Section 2.7, using homogeneous binary/Gaussian input. Shown are color-coded performance sweeps for the XOR-performance (18), averaged over five trials. The input has variance  $\sigma_{\text{ext}}^2$  and the target for the spectral radius  $R_t$ . A/B panels are for binary/Gaussian input protocols. Optimal performance for a given  $\sigma_{\text{ext}}$  is given by yellow solid lines, measured value of  $R_a = 1$  by white dashed lines.





**Figure S10. Input induced activity correlations.** For homogeneous binary and Gaussian inputs (A/B), the dependency of mean activity cross correlations  $\bar{C}$ , see Eq. (20).  $\bar{C}$  is shown as a function of the target spectral radius  $R_a$ . Results are obtained for  $N = 500$  sites by averaging over five trials, with shadows indicating the accuracy. Correlations are due to finite-size effect for the autonomous case  $\sigma_{\text{ext}} = 0$ .



**Figure S11. Diagonal Elements of a randomly generated covariance matrix and its representation in the  $\hat{S}_u$  basis.**  $\hat{C}_{yy}$  is a diagonal matrix with diagonal entries randomly drawn from  $[0, 1]$ ,  $\hat{S}_u$  is the orthonormal eigenbasis of  $\hat{W}_a^\dagger \hat{W}_a$ , where  $\hat{W}_a$  is a random Gaussian matrix. The black dashed line denotes the average over the diagonal entries of  $\hat{C}_{yy}$ .