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Parking and competition for space in urban neighborhoods: Residents' perceptions of traffic and parking-related conflicts

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Abstract: The infrastructure for parking and parked cars themselves (e.g., parked cars blocking bike lanes and sidewalks or the visibility range) can lead to conflicts for pedestrians and cyclists. The perception of conflicts could discourage walking and cycling in neighborhoods and undermine municipalities' efforts to provide more sustainable urban mobility. The aim of this study was therefore to analyze the effect of on-street car parking in urban neighborhoods on perceived parking and traffic-related conflicts. In addition, it examines in what way the intention to reduce one's car use influences the perception of the conflicts (Stage Model of Self-Regulated Behavior Change (SSBC)). A household survey was conducted in the inner-city neighborhood of Frankfurt-Bornheim, Germany (N=1027). The residents most often observed the conflicts in which parked cars impeded walking and cycling as well as situations in which pedestrians felt threatened by cyclists biking on the sidewalk. Results from multiple linear regression models revealed that the influencing factors for the perception of conflicts were the use of different means of transportation and the intention to change one's behavior (SSBC model) to reduce car use rather than car ownership. In addition, a resident's age and household structure seemed to affect awareness of conflicts in which pedestrians and cyclists were involved. The results suggest a group-serving bias, meaning that the residents mostly observed those conflicts that they did not cause. A separate infrastructure for pedestrians and cyclists could help prevent most of the conflicts described in this study.

1 Introduction

Present planning for car-oriented cities has led to a car-dependent transport system in most North American and European cities. They contain a high amount of car and parking infrastructure as well as high levels of private car ownership (Mattioli, Roberts, Steinberger, & Brown, 2020). When most travel is carried out by cars, the resulting traffic congestion compromises the efficiency of the transportation system and the city's quality of life (Vuchic, 2010). Furthermore, car-oriented cities usually neglect pedestrian infrastructure and offer ample free parking (Chester, Horvath, & Madanat, 2011; Manville & Pinski, 2020; Weinberger & Jacobson, 2014).

In urban areas the number of people who regularly use alternatives to the private car is increasing

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steadily. Yet, land allocation and infrastructure for active travel mostly stays at the same level (Infas & DLR, 2019; Kuhnimhof, Buehler, Wirtz, & Kalinowska, 2012; Le, Buehler, & Hankey, 2019). The infrastructure for parking and parked cars themselves can be a conflict risk for pedestrians and cyclists as many accidents in the US involve parked cars (Schlossberg & Amos, 2015). The risk of accidents varies between different types of neighborhoods, i.e., whether they are areas characterized by high or low residents' vehicles miles travelled (Merlin, Cherry, Mohamadi-Hezaveh, & Dumbaugh, 2020). In addition, the risk increases on local roads with low visibility, for instance at intersections (Becker, 2016; Bracher, 2014; Findley et al., 2020). Moreover, the land consumption of parked cars can lead to conflicts between traffic participants and they can represent a danger to pedestrians when vehicles cross sidewalks to get to parking lots or parking garages. Parked cars can also increase the separating effect of streets because they hinder the crossing of roads for pedestrians, for people with luggage, and for cyclists. Furthermore, parking supply affects residents' decision about car ownership and car use (Chester et al., 2011; Manville & Shoup, 2018; Notz, 2017; Vuchic, 2010; Weinberger, 2018; Weinberger & Jacobson, 2014). In addition, in a literature review from studies across the world, Jacobsen, Racioppi, and Rutter (2009) discovered that the perception of the risks of conflicts may discourage residents from walking and cycling. This again leads to car use and, consequently, to cars that need to be parked. Notz (2017) points out that while the importance of sustainable mobility and recognizing public space is gaining momentum, parked cars are not problematized in public discourse in Germany but are rather seen as a necessary normality.

Therefore, the aim of this research is to analyze empirically the effect of on-street car parking in urban neighborhoods on perceived parking and traffic-related conflicts. Here, conflicts are defined as threatening and dangerous situations between traffic participants from the perspective of the participants. If we know more about the perception of the conflicts, we can better evaluate the implications the conflicts have on different resident groups and their mobility behavior. The paper looks at car parking as one form of land use by examining how urban space is currently used and whether this leads to conflicts with subsequent consequences.

Thus, a household survey (N=1027) in an inner-city neighborhood in Frankfurt, Germany, was conducted to answer the following research questions: (1) To what extent do residents perceive different parking and traffic-related conflicts? (2) In what way does car and bike ownership, and the use intensity of different means of transportation influence the perception of the conflicts? (3) How do the car-owning residents, who park their cars in the neighborhood, perceive the conflicts? (4) In what way does the intention to reduce car use influence the perception of the conflicts? Building upon other studies, which worked with the Stage Model of Self-Regulated Behavior Change (SSBC), and which showed that the intention towards reduced car use reveals a differentiation between car owners (e.g., Blitz, Busch-Geertsema, & Lanzendorf, 2020; Kirschner & Lanzendorf, 2020a), this analysis assesses whether this intention has an influence as well. In addition, the influence of five control variables on the perception are analyzed (gender, age, household structure, income, university degree).

Subsequently, the hypotheses to be tested are the following: Residents observe parking-related conflicts between different traffic participants (H1). Car ownership has an influence on the perception of the conflicts (H2). Bike ownership has an effect on the perception of conflicts (H3). Differences in the usage rates of means of transportation affect awareness of the conflicts (H4). The residents who own cars and need to park these perceive the conflicts differently from residents who live car-free (H5). Classification into the SSBC model produces differences in the perception of conflicts (H6).

This paper is structured as follows: after a review of the literature about space allocation and the perception of risk and conflicts, the case study and methods are presented in section 3. Section 4 covers the results of the perception of conflicts in general, of the findings of the multivariate analysis regarding

all households and the classification into the SSBC model, as well as the results for the residents with car ownership. Finally, section 5 discusses the findings and closes with conclusions.

2 State of the art

2.1 Space allocation in urban neighborhoods

Urban space is a scarce resource. Different means of transportation have different requirements and so they compete for the urban space. Pedestrians and their way of using public space (walking, strolling, or staying in a place to talk) are in competition for space with moving and parked cars (Alrutz & Bohle, 2001; Norton, 2008). In addition, although pedestrians and cyclists have in common a long neglection from planning due to car-oriented urban planning, but because of their different infrastructure needs, they are still in competition with each other for (a high quality of) road space and political attention (Banister, 2008; Bracher, 2014; Litman, 2019). Compared to cars, pedestrians and cyclists require less space to move and, in the case of cycling, for parking. According to Norton (2008), the current arrangement of street space is the result of a technical and social reconstruction of the street for the car. Most cities coped with the increasing number of vehicle traffic in the 20th century by using open public space for roads and for parking requirements and especially large parking areas impede the potentially different uses of public roads and lead to a loss of the pedestrian scale (Bracher, 2014; Gehl, 2010; Jacobsen et al., 2009).

On the other hand, cities can move parking to central garages at the edge of a neighborhood or underground to recapture traffic space as social space and design neighborhood streets almost completely car free (Dürr & Simon-Philipp, 2013). Moreover, by eliminating subsidized and free parking in central areas and excluding parking on sidewalks, cities can create attractive pedestrian areas and extend the bike lane network (Goldman & Gorham, 2006; Vuchic, 2010). In conclusion, due to diverging interests, a well-used public space is also always a conflictual space (Dürr & Simon-Philipp, 2013). However, currently, the multi-functionality of public space in urban neighborhoods (traffic, residential environment, communication platform) is not visible in its allocation for different uses as parked cars use public space disproportionately to the modal split (Gössling, Schröder, Späth, & Freytag, 2016; Nello-Deakin, 2019). Pedestrians and cyclists, on the other hand, may save space, help reduce air pollution, and thereby contribute to the quality of life in a neighborhood (Gehl, 2015; Notz, 2017).

2.2 Motorized traffic and parking as a safety risk

Safety problems on the road started around 100 years ago. Before the arrival of the car, pedestrians and cyclists were able to use the whole street but this situation changed when motorized cars arrived in the city and neighborhood streets, and fatalities became frequent. Most of the victims were pedestrians and cyclists, and a majority of those were children and young people (Cox, 2012; Jacobsen et al., 2009; Norton, 2008).

Today, we still face similar problems. In the US, motor vehicle accidents with moving and parked cars account for half of all accidental deaths, and, in Germany, there are more than 3,000 yearly traffic deaths (Federal Statistical Office, 2020; Gifford & Steg, 2007). Pedestrians and cyclists are at risk in particular. For instance, pedestrians account for a higher percentage of traffic fatalities in the US than their share of road use. In addition, speed differentials between modes have a profound effect on the safety of pedestrians and cyclists (Culver, 2018; Ewing & Dumbaugh, 2009). Moreover, the likelihood to be involved in a crash depends on the type of neighborhood and its destination accessibility (Merlin

et al., 2020). In sprawling neighborhoods, the overall fatality rates and the rate of pedestrian fatalities are higher than in denser areas, where the average speeds are lower and the uninterrupted length of a roadway is shorter. In other words, overall, narrow streets with a slow speed are safer for pedestrians and cyclists (Ewing & Dumbaugh, 2009; Malin, Silla, & Mladenović, 2020). However, many accidents to pedestrians in these fabrics happen while trying to cross a street or a road (Malin et al., 2020). The risk of accidents increases with low visibility, for instance, due to parked cars or during parking maneuvers (Bracher, 2014; Findley et al., 2020). For example, more than two-thirds of accidents on local streets in the US involve parked cars that were parked on-street (Schlossberg & Amos, 2015). Especially at intersections, parked cars lead to reduced visibility for all traffic participants. Thus, one part of parking management is to ban parking around intersections as to increase the visibility of pedestrians and cyclists for car drivers (Becker, 2016). Furthermore, a cause of incidents between cyclists and vehicles is so-called dooring. This happens when passengers open vehicle doors into the path of cyclists without looking over their shoulder (Ewing & Dumbaugh, 2009; Pai, 2011).

2.3 The perception of risks among different groups

Particular risk groups are children and older people. Drivers miss seeing children, especially when they dart out from between parked cars. Older people tend to avoid perceived unsafe areas with high traffic, such as unmarked crosswalks (as opposite of zebra crossings), and they cannot react as quickly anymore when obstacles are on the sidewalk (Ewing & Dumbaugh, 2009; Harms et al., 2009; Jacobsen et al., 2009). Harms et al. (2009) observed that, apart from the elderly, people from car-free households have the highest perception of risk with respect to parked cars and cyclists on sidewalks as they feel like parked cars take away their pedestrian space. In addition, they discovered that the subjective perception of risks on sidewalks is not necessarily congruent with the amount of counted (near) collisions in different areas within a neighborhood. Furthermore, Chataway, Kaplan, Nielsen, and Prato (2014) studied the safety perceptions from different modes. They reported the behavior of cyclists in mixed traffic, focusing on infrastructure and coping strategies. Several studies explore the safety of infrastructure with a focus on visibility in moving traffic, e.g., perceived risk in bike-car interactions (Chaurand & Delhomme, 2013), and perceived risk with low visibility conditions (King, Wood, Lacherez, & Marszalek, 2012; Wood, Lacherez, Marszalek, & King, 2009).

In conclusion, a real and perceived risk of conflicts with moving and parked cars may discourage walking and cycling in neighborhoods (Jacobsen et al., 2009). Although fatalities caused by motorized-traffic are well known and documented in governmental statistics, they are seldom problematized. Culver (2018) calls the violence of the car a "blind spot" (p. 146) in transportation and mobility research. So far, most studies analyzed conflict perceptions in moving traffic, and perceived safety of infrastructure layouts or risk potentials under low visibility (e.g., Chataway at al., 2014; Chaurand & Delhomme, 2013; King et al., 2012; Wood et al., 2009). This study tries to shed new light on traffic participants' conflict perceptions with a focus on parking, specifically on parking in urban neighborhoods.

3 Materials and methods

3.1 Case study

The neighborhood of Bornheim is the case study of this household survey. It is centrally located in the city of Frankfurt, and, with approximately 30,000 inhabitants, it is among the neighborhoods with the highest population densities in the city (City of Frankfurt, 2019a). At the time of the survey, on-street parking was unlimited in most parts of the neighborhood without any time or financial restrictions.

In the southern part, there was a parking scheme with residential parking permits. Such permits cost twenty-five euros per year. The scheme states, however, that not all on-street parking spaces are reserved for permit holders, but, instead, fifty percent of the available on-street parking space still needs to be accessible in an unlimited way (Kirschner & Lanzendorf, 2020b). In the meanwhile, the administration implemented a neighborhood wide parking concept, which extends the current regulations to the whole neighborhood (City of Frankfurt, 2019b). In terms of alternative means of transportation, the neighborhood is well served by multiple subway, tram, and bus lines that connect the neighborhood to the central station. Several officially designated bike lanes run through the neighborhood. Furthermore, there are carsharing and bike sharing stations throughout the neighborhood. The speed limit is 50 km/h (\approx 30 mph) on main roads in cities and 30 km/h (\approx 19 mph) for residential streets.

The sample reveals that almost forty percent of households in the neighborhood do not own a private car (Table 1). In comparison, in Germany as a whole, twenty percent of households live car-free, and we find the highest number (forty percent) in the main cities (Infas & DLR, 2019). Of the sixty percent of households with private cars in Bornheim, around half of them park their cars off-street in their own parking spaces or in garages and another fifty percent uses on-street parking as well as the residential parking permits. In addition, residents show high rates of walking, the majority regularly uses public transit, and there is a similar usage rate for cars and bicycles. Although the car is not the main means of transportation among residents in the neighborhood, as in similar central neighborhoods of other cities, parked cars dominate the image of the streets and, often, of the sidewalks as well (Figure 1). The mean occupancy rate of on-street parking space in the neighborhood differs for each street and is between 75% and over 90% (measured between 6am and 10pm; City of Frankfurt, 2014). On-street parking does not automatically legally include fully parking on the sidewalk as shown in Figure 1 in the photo on the left. Only in some streets it is legally allowed. However, in almost all parts of the neighborhood, cars partially park on the sidewalk to fit into the street size and width. The width of the sidewalks differs between 2m in mostly residential streets and up to 7m in the main connecting roads throughout the neighborhood (City of Frankfurt, 2020).



Figure 1. Impressions of the case study of Frankfurt-Bornheim (photos by author)

Regarding socio-demographics, in comparison to available data statistics for the neighborhood and the whole city, our sample has a higher percentage of female participants, older people, and large households (Table 2).

Variable	Description	Mean	SD
Ownership			
Households without car ownership	No car $(1); \ge 1$ car (0)	0.39	0.488
Private bicycle ownership	No (0); yes (1)	0.72	0.448
Transport modes: Regular ¹ users of			
private car as driver	Non-regular use (0); regular use (1)	0.45	0.498
public transit	Non-regular use (0); regular use (1)	0.67	0.471
bicycle	Non-regular use (0); regular use (1)	0.47	0.499
walking ²	At a non-regular level (0); at a regular level (1)	0.88	0.324
Residential parking (residents from car owning househol	ds only, N = 627)		
Users of residential on-street parking	Own parking space and rented off-street parking (0);	0.56	0.497
	on-street parking and parking permit (1)		
¹ Regular use: (almost) daily – 1-3 days/week			
² We excluded walking from further multivariate analysis du	e to high walking rates and low variation.		

Table 1. Descriptive statistics of mobility-related variables used for the analysis (N=1027)

Table 2. Socio-demographic statistics of variables used for the analysis (N=1027) in comparison to available city statistics

Socio-demographics		San	nple	Bornheim	Frankfurt
Variable	Description	Mean	SD	Mean	Mean
Gender: male*	Female (0); male (1)	0.40	0.49	0.47	0.50
Mean age*1	Age in years (18-92)	50.5	15.5	42.7	40.8
University degree	No (0); yes (1)	0.55	0.49	no data	no data
Families with children*2	Families without children (0); families with children (1)	0.16	0.36	0.15	0.18
Net monthly income (mean value 200-6.000€) ³	Income in Euro	2,299.41	1129.48	no data	no data
		N =	1,027	N = 30,533	N = 747,848

*Significant difference between sample and total population of Bornheim, and total population of city of Frankfurt; binomial test, p < .001

¹Note that the age of the survey participants is \geq 18 years while the base for the mean age of Bornheim and the city of Frankfurt starts at aged 0.

 2 Note that "children" in the survey is defined as being < 14 years while the city administration does not define whether the threshold is at < 14 or at < 18 years.

³Quotient of the mean value of the monthly net household income (using the levels: less than 1000, 1000 to less than 2500, 2500 to less than 4000, 4000 to less than 5500, 5500 and more) and the number of household members (adjusted according to the OECD-modified scale (OECD, 2016): value of first adult = 1.0, each further adult = 0.5, each child under 14 years = 0.3 (OECD)

3.2 Data

The household survey was part of a larger project about persistency and change in urban neighborhoods. The survey was cross-sectional and we conducted it in March 2018. 3,000 surveys were distributed and the return rate was thirty-four percent (N=1027). I used random route sampling and the last birthday method for distribution and household selection (Binson, Canchola, & Catania, 2000; Diekmann, 2017; Fuller, 2009; Kirschner, 2019). The survey included six blocks: life in Bornheim, availability of means of transportation, frequency of use of means of transportation, mobility in Bornheim, policy options in Bornheim, and socio-demographics.

To measure parking and traffic-related conflicts in the neighborhood, the structure of the conflict items was based on Harms et al. (2009), who conducted a survey about parking in a neighborhood in Leipzig, Germany. The items directly or indirectly relate to conflicts with parked cars. Those items, which do not include parked cars in their description but solely pedestrians and cyclists, are related to parking indirectly via the land that has been dedicated to parked cars. First, I measured the items for the perceived conflicts using a five point Likert-type scale ranging from "strongly agree" to "strongly disagree."

Second, I conducted a principal component analysis (PCA) for the twenty-one conflict items. The PCA analysis revealed four factors with eigenvalues greater than one (Table 3). Factor 1 "Pedestrians are impeded by car traffic and parking" describes conflicts pedestrians may experience due to parked cars. Factor 2 "Cyclists are vulnerable with respect to car traffic and parking" is analogous to factor 1 and includes conflicts with and due to parked cars perceived from a cyclist's perspective. The third factor "Pedestrians are impeded by bicycles on the sidewalk" is composed of conflicts pedestrians have with cyclists and bike racks on the sidewalk. The fourth factor "Car drivers' perceived conflicts with others" are conflicts, perceived from the car drivers' view, with other traffic participants, i.e., other car drivers, pedestrians, and cyclists.

Third, to analyze the intention to change one's behavior, I use the stage model of self-regulated behavior change (SSBC) (Bamberg, 2012, 2013). It includes the theory of planned behavior (Ajzen, 1991) and the norm activation model (Schwartz, 1977) and is based on the transtheoretical model (DiClemente & Prochaska, 1982; Prochaska & DiClemente, 1983). Alongside car and bicycle ownership as well as regular use of different means of transportation (Table 1), the aim is to assess whether the intention to reduce personal car use has an influence on the perception of the conflicts. The SSBC understands behavior change as a process of four stages. While residents in stage one are currently satisfied with their behavior and see no reason to change, residents in the fourth stage already use their private car less often and instead use other means of transportation. I assign residents who live in households without private cars to the residents in the postactional stage, as their car use is low as well and as they mostly make use of public transit and bicycles (see Kirschner & Lanzendorf, 2020a, for a detailed description).

To assign the residents into the four stages, as part of the survey, the participants were asked to indicate their personal assessment with a 5 point Likert scale of nine different questions (Figure 2). Each question referred to an underlying construct as part of one of the stages (Bamberg, 2012). The final classification of the residents into the four stages are shown in Figure 3.



Figure 2. Questions for the stage assignment of the SSBC model (based on Bamberg, 2012)



Figure 3. Stage model of self-regulated behavior change towards reduced private car use; shown are the classification of survey participants into each stage, as well as each car, public transit, and bicycle usage rate (own diagram, based on Bamberg, 2013)

4 Results

4.1 The perception of parking and traffic-related conflicts of residents in an urban neighborhood

Table 3 shows the perception of conflicts for each of the twenty-one conflict items. The conflicts the residents observe most often are those in which parked cars impede walking and cycling, as well as when pedestrians feel threatened by cyclists who bike on the sidewalk. The conflict items the residents perceive least often are when bicycle parking lots are on sidewalks and the overall risk of an accident as a pedestrian. In addition, the residents observe individual conflict items of the factor "Car drivers" perceived conflicts with others" the least often compared to the other three factors. The factor "Cyclists are vulnerable with respect to car traffic and parking" consists of the individual conflict items which the residents are aware of most often.

Table 3. Principal component analysis and initial items of perceived parking and traffic-related conflicts in the neighborhood (N=1027)

			Factors			
Items regarding perceived conflicts Items measured on a five point Likert scale: (1) strongly agree – (5) strongly disagree In Bornheim	Mean	SD	Pedestrians are impeded by car traffic and parking	Cyclists are vulnerable with respect to car traffic and parking	Pedestrians are impeded by bicycles on the sidewalk	Car drivers' perceived conflicts with others
as a pedestrian, parked cars often impede walking.	2.81	1.16	.831	.249	.026	017
as a pedestrian, I often have to change my path because cars park on the sidewalk.	3.00	1.18	.815	.238	.044	016
as a pedestrian, parked vehicles are a safety risk because approaching cars cannot see me easily when I want to cross the street.	3.08	1.15	.714	.297	.094	.107
as a pedestrian, I often feel vulner- able with respect to car drivers, who do not pay attention to pedestrians while parking.	3.42	1.02	.698	.251	.195	.081
it is difficult to walk with a buggy, walking aid or a suitcase because sidewalks are not lowered.	2.97	1.07	.679	.043	.114	.131
parked cars increase the risk of an accident for pedestrians and cyclists.	2.98	1.12	.663	.337	.027	068
risk of an accident as a pedestrian is high.	3.67	0.99	.655	.066	.247	.088
many sidewalks are too narrow.	2.94	1.14	.651	.107	.115	.095
as a pedestrian, I often feel vulner- able at intersections when I want to cross an intersection straight ahead and cars want to make a turn.	3.28	1.06	.621	.304	.114	.171
as a cyclist, I often feel vulnerable with respect to car drivers, who do not pay attention to cyclist while parking.	2.94	1.29	.187	.854	044	.072
as a cyclist, I often feel vulnerable at intersections when I want to cross an intersection straight ahead and cars want to make a turn.	3.00	1.26	.164	.842	038	.096
as a cyclist, parked vehicles are a safety risk because approaching cars cannot see me easily when I want to cross the street.	3.13	1.32	.251	.829	.001	.076
as a cyclist, I often have to change my route because cars are parked on the bike lane.	2.96	1.29	.254	.813	062	.019
often, parked cars impede cycling.	2.90	1.27	.306	.803	072	.015
as a cyclist, the risk of accidents is high.	3.07	1.22	.158	.729	.057	.011

			Factors			
Items regarding perceived conflicts Items measured on a five point Likert scale: (1) strongly agree – (5) strongly disagree In Bornheim	Mean	SD	Pedestrians are impeded by car traffic and parking	Cyclists are vulnerable with respect to car traffic and parking	Pedestrians are impeded by bicycles on the sidewalk	Car drivers' perceived conflicts with others
as a pedestrian, I get annoyed by bicycles that are parked on the sidewalk.	3.45	1.29	.202	.012	.875	.018
as a pedestrian, I do not welcome bicycle parking lots on the sidewalk.	3.83	1.22	.104	043	.871	.011
as a pedestrian, cyclists, who bike on the sidewalk, threaten me.	2.87	1.27	.242	076	.733	.013
I sometimes get in conflicts with other car drivers who are also search- ing for a parking lot. ^{<i>a</i>}	3.89	0.87	.006	.035	.030	.755
as a driver, I sometimes get in con- flicts with pedestrians or cyclists. "	3.90	0.87	.101	.025	.182	.688
I sometimes get the feeling I hin- der other people with my parked car. "	4.04	0.80	.153	.102	183	.584
Eigenvalues			7.3	3	1.5	1.5
% of variance			35	14.2	7.1	6.9
Total explained variance				63.	2%	
DCA	1 1 1.	(0 (1	· <u>v</u> ·	,	0 000 D .1?	

PCA with varimax rotation; eigenvalues > 1; loadings \leq 0.4 shown in grey; Kaiser's criterion = 0.900; Bartlett's test of Sphericity: X² = 7327.8, df = 210, p = 0.000; N = 1027 (Field, 2018; Stevens, 2002).

^a Only residents from car ownings households answered these questions. We replaced missing values with the mean value.

4.2 The effect of residents' characteristics on the perception of parking and traffic-related conflicts

Following the previous analysis, I assess to what extent resident characteristics have an effect on the perception of the conflict factors: the intention to change one's behavior to reduce car use (SSBC), the ownership of cars and bikes, the regular use of different means of transportation, and socio-demographics as control variables (Table 4). The factors "Pedestrians are impeded by car traffic and parking" and "Cyclists are vulnerable with respect to car traffic and parking" are more frequently mentioned by residents in the postactional stage of the SSBC model of car use, residents from households without private cars and residents who regularly cycle. Residents in the predecisional stage and those who regularly drive, on the other hand, observe these conflicts less often. In addition, regular public transit users notice the conflicts between pedestrians and car traffic more often than the residents who do not regularly use public transit. Residents who own bicycles observe the conflicts between cyclists and car drivers more frequently but not the conflicts between pedestrians and cyclists. Furthermore, residents in the preactional and actional stages as well as regular car users more often observe conflicts from a car drivers' perspective, whereas residents in the postactional stage perceive those less frequently. Moreover, the data reveals that older residents perceive the conflicts pedestrians experience more frequently than the conflicts between cyclists and car drivers. Families with children more frequently observe the conflicts pedestrians and cyclists may have with cars but less often the conflicts between pedestrians and cyclists.

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	Pedestrians are impeded by car traffic and parking N = 1027	Cyclists are vulnerable with respect to car traf- fic and parking N = 1027	Pedestrians are impeded by bicycles on the sidewalk N = 1027	Car drivers' per- ceived conflicts with others N = 1027			
Stages of the SSBC model							
Predecisional stage	-0.39**	-0.26**	0.31**	0.10			
Preactional and actional stages	0.07	-0.01	0.10	0.55**			
Postactional stage	0.15**	0.10**	-0.13**	-0.07**			
Ownership							
Households with car ownership	-0.14**	-0.06*	0.03	0.03			
Households without car ownership	0.22**	0.09*	-0.05	-0.04			
Private bicycle ownership	-0.01	0.22**	-0.17**	-0.00			
No private bicycle ownership	0.04	-0.56**	0.44**	0.00			
Regular use of means of transportation							
Car as a driver	-0.22**	-0.09**	0.09**	0.96**			
Public transit	0.04*	-0.01	-0.01	-0.00			
Bicycle	0.10**	0.27**	-0.39**	0.00			
Socio-demographics							
Gender (male)	0.05	-0.01	0.05	-0.06			
Gender (female)	-0.03	0.00	-0.03	0.04			
Age (18-29 years)	-0.27*	0.10	-0.18	0.16			
Age (30-64 years)	0.02	0.08**	-0.12**	0.00			
Age (65+ years)	0.17**	-0.34**	0.49**	-0.07			
Families with children < 14 years	0.17*	0.22**	-0.33**	0.01			
Families without children < 14 years	-0.03*	-0.04**	0.06**	-0.00			
Net monthly income (< 1.000€)	0.11	-0.18*	0.20*	0.06			
Net monthly income (1000€ to < 2.500€)	0.03	0.05	0.04	0.02			
Net monthly income (2.500€ to < 4.000€)	-0.04	0.01	-0.07	-0.04			
Net monthly income (> 4.000€)	-0.16	-0.05	-0.23*	-0.05			
University degree	-0.06*	0.13**	-0.22**	0.06*			
No university degree	0.07*	-0.16**	0.27**	-0.07*			
All residents	0.00	0.00	0.00	0.00			
Significant difference within each resident characteristic, Pearsons's r, ** p < 0.00, * p < 0.05							

Table 4. Mean value comparison of the perception of conflicts for different resident groups

Second, using multiple linear regression analyzes (OLS)¹, according to the research questions, I tested how the different ownership and use of different means of transportation, as well as the behavior change intention affected the perception of the conflicts. The explained variances vary between the

¹ Each model was tested for multicollinearity. The models were adequate, with Pearsons' correlation coefficient < 0.8, tolerance value > 0.1, and variance inflation factor < 10 (Backhaus et al., 2018; Cohen et al., 2003).

models, with the highest for the conflicts that pedestrians experience with cyclists on the sidewalk and the lowest for "Car drivers' perceived conflicts with others" (Table 5).

Residents who are in the postactional stage tend to perceive the conflicts pedestrians and cyclists may have with car traffic and parking more often than residents who are in any of the other stages of the model. On the other hand, these residents in the postactional stage notice less often the conflicts, which occur when pedestrians feel impeded on the sidewalk by cyclists, and the conflicts car drivers may experience. Not owning a private car does not affect the probability of perceiving any of the conflicts in these models. Owning a bicycle more often affects the perception of the conflicts cyclists may have with car traffic and parking. Regarding the regular use of different means of transportation, the regular use of public transit is not critical for awareness of the conflicts in this case study, whereas the use of a car as a driver and the use of a bicycle appear to contrarily influence the perception of the conflicts around pedestrians.

Finally, regarding the control variables, an older age decreases the possibility of observing the conflicts cyclists may experience with cars. Besides, residents who live in households with children observe the situations pedestrians experience with car traffic and parked cars more than those living without children.

	Pedestrians are impeded by car traffic and parking	Cyclists are vulnerable with respect to car traffic and parking	Pedestrians are impeded by bicycles on the sidewalk	Car drivers' perceived conflicts with others
Stages of SSBC [Reference: households with car ownershi	p, stages 1-3]			
Households with and without car ownership in postactional stage (1 = yes; 0 = no)	0.103**	0.089**	-0.136***	-0.113**
Ownership				
Households without car ownership (1 = yes; 0 = no)	0.065	0.056	0.027	0.065
Private bicycle ownership $(1 = yes; 0 = no)$	-0.045	0.307***	-0.031	-0.014
Regular ¹ use of means of transportation				
Car as a driver $(1 = yes; 0 = no)$	-0.099**	-0.017	0.035	0.087
Public transit (1 = yes; 0 = no)	0.008	-0.018	0.022	0.036
Bicycle (1 = yes; 0 = no)	0.104**	0.042	-0.262***	0.023
Socio-demographics				
Gender (1 = male; 0 = female)	0.070**	-0.009	0.048*	-0.054*
Age	0.146***	-0.061*	0.187***	-0.053
Families with children < 14 years				
(1 = yes; 0 = no)	0.129***	0.024	-0.050*	-0.019
Net monthly income	0.006	-0.070**	-0.044	-0.055
University degree (1 = yes; 0 = no)	-0.051	0.063*	-0.096**	0.074**
R ²	0.102	0.157	0.223	0.029
corrected R ²	0.092	0.147	0.214	0.019
F-statistic	0.000***	0.000***	0.000***	0.001**
Ν	1027	1027	1027	1027

Table 5. OLS regression models for parking and traffic-related conflicts in the neighborhood

¹ Regular use: (almost) daily – 1-3 days/week

Factors from PCA analysis as dependent variables. Beta coefficients are shown.

*** p < 0.00, ** p < 0.05, * p < 0.10

4.3 Conflicts of residents with private car ownership

The classification of residents with private cars into the different stages of intention to change one's behavior towards reduced car use has broadened the results of earlier studies. It is also of interest for this study to analyze these residents in detail because they are the residents who park their cars in the neighborhood and thus may cause some of the conflicts discussed here. The analysis has so far shown that while there is no difference in the conflict perception between residents with and without private cars, the perception distinction within car-owning households differs along the classification into the SSBC model. Therefore, in the following section, I analyze the conflict awareness of the residents from households with private car ownership in detail.

When comparing the mean values of the conflict items with those of all residents (Table 6), there are no changes in the significances for the SSBC stages and for bicycle ownership. Yet, there are differences between all residents and those with car ownership for the perception of the conflicts regarding the usage rates of cars and bicycles. The awareness of the conflicts "Pedestrians are impeded by car traffic and parking" is lowered among regular bike users when comparing it to the average of all residents, but it is still above the average of the residents with private cars only. Moreover, the perception of regular car users of the conflicts "Cyclists are vulnerable with respect to car traffic and parking" is not significant anymore in comparison to car users among all residents. Furthermore, regarding the control variables, the data reveals that fewer differences within the residents' characteristics are significant and that most changes result for the conflicts "Pedestrians are impeded by car traffic and parking."

As a sequence of Table 5, I calculated OLS models for each conflict factor. Table 7 displays the four models for all residents from households with private car ownership. Again, as in Table 5, the explained variances differ between the models and here they are higher for models 2-4 than in the models for all residents. Bicycle ownership and different usage patterns of means of transportation have a similar effect on the perception of the conflicts. The same holds true for the classification into the SSBC model, i.e., except for slight changes in the coefficients' strength, the effects are similar to those for all residents. However, changes occur for some control variables. For instance, here, age is not critical for the awareness of conflicts between cyclists and car traffic.

	Pedestrians are impeded by car traffic and parking N = 627	Cyclists are vulnerable with respect to car traf- fic and parking N = 627	Pedestrians are impeded by bicycles on the sidewalk N = 627	Car drivers' per- ceived conflicts with others N = 627
Stages of the SSBC model				
Predecisional stage	-0.39**	-0.26**	0.31**	0.10
Preactional and actional stages	0.08	0.01	0.10	0.55**
Postactional stage	0.05**	0.12**	-0.22**	-0.11**
Ownership				
Private bicycle ownership	-0.14	0.14**	-0.12**	0.03
No private bicycle ownership	-0.16	-0.69**	0.54**	0.01
Regular use of means of transportation				
Car as a driver	-0.23**	-0.10	0.10**	0.10*
Public transit	0.07*	-0.09	0.04	0.03
Bicycle	-0.02**	0.17**	-0.41**	0.05
Socio-demographics				
Gender (male)	-0.08	-0.09	0.12	-0.06
Gender (female)	-0.19	-0.03	-0.03	0.09
Age (18-29 years)	-0.52**	0.03	-0.19	0.31
Age (30-64 years)	-0.13	0.00**	-0.06**	0.03
Age (65+ years)	-0.04	-0.36**	0.55**	-0.09
Families with children < 14 years	0.12**	0.23**	-0.35**	0.02
Families without children < 14 years	-0.21**	-0.13**	0.13**	0.03
Net monthly income (< 1.000€)	-0.05	-0.15	0.29	0.16
Net monthly income (1000€ to < 2.500€)	-0.13	-0.06	0.06	0.06
Net monthly income (2.500€ to < 4.000€)	-0.12	0.01	-0.02	-0.04
Net monthly income (> 4.000€)	-0.34	-0.19	-0.21*	-0.04
University degree	-0.21	0.06**	-0.19**	0.13*
No university degree	-0.06	-0.20**	0.31**	-0.11*
All residents with private cars in their households	-0.14	-0.06	0.03	0.03

Table 6. Mean value comparison of the perception of conflicts for residents with private car ownership

	Pedestrians are impeded by car traffic and parking	Cyclists are vulnerable with respect to car traffic and parking	Pedestrians are impeded by bicycles on the sidewalk	Car drivers' per- ceived conflicts with others
Stages of SSBC [Reference: households with car own	nership, stages 1-3]			
Households with car ownership, postactional stage (1 = yes; 0 = no)	0.115**	0.112**	-0.129**	-0.108**
Ownership				
Private bicycle ownership (1 = yes; 0 = no)	-0.055	0.317***	-0.021	-0.005
Regular ¹ use of means of transportation				
Car as a driver $(1 = yes; 0 = no)$	-0.085**	-0.009	0.051	0.069
Public transit (1 = yes; 0 = no)	0.046	-0.039	0.046	0.044
Bicycle $(1 = yes; 0 = no)$	0.107**	0.008	-0.295***	0.045
Socio-demographics				
Gender (1 = male; 0 = female)	0.082**	-0.022	0.053	-0.056
Age	0.115**	-0.056	0.190***	-0.068
Families with children < 14 years				
(1 = yes; 0 = no)	0.157***	0.064	-0.063*	-0.030
Net monthly income	0.010	-0.062	-0.047	-0.073*
University degree $(1 = yes; 0 = no)$	-0.080*	0.039	-0.093**	0.102**
R ²	0.095	0.162	0.255	0.038
corrected R ²	0.081	0.149	0.243	0.023
F-statistic	0.000***	0.000***	0.000***	0.007**
Ν	627	627	627	627

Table 7. OLS regression models for parking and traffic-related conflicts in the neighborhood for all residents with private cars in their households

¹ Regular use: (almost) daily - 1-3 days/week

Factors from PCA analysis as dependent variables. Beta coefficients are shown.

*** p < 0.00, ** p < 0.05, * p < 0.10

5 Discussion and conclusion

The aim of this paper was to examine the residents' perception of conflicts caused by parked cars as one prevalent current land use in an urban neighborhood. The residents most often perceive conflicts in which parked cars impede cyclists and pedestrians. In addition, as pedestrians, the residents often feel threatened when cyclists bike on the sidewalk. The conflicts the residents observe the least often are situations in which bicycle parking lots are on the sidewalks, and the overall risk of an accident as a pedestrian. Moreover, all the conflicts drivers perceive with other traffic participants investigated in this study were observed the least often (H1).

5.1 The behavior change model as an indicator of conflict perception

This study discovered that just car ownership does not have an effect on the perception of the conflicts (H2). It revealed, however, that bicycle ownership is critical for the awareness of the conflicts between cyclists and car drivers (H3). Regarding the use of different means of transportation, residents who

regularly cycle perceive the conflicts "Pedestrians are impeded by car traffic and parking" more often than residents who do not regularly use a bicycle. At the same time, regular car drivers perceive these conflicts less often than residents who do not regularly drive (H4). This is in contrast to the results from Chaurand & Delhomme (2013) who discovered the perceived risk in road interactions between cyclists and car drivers was higher for drivers than for cyclists. The detailed analysis of the residents with private cars showed partially different effects of the other resident characteristics on the perception of the conflicts. Their bicycle ownership and use patterns of means of transportation stayed similar in their effect compared to all residents (H5). Furthermore, this study revealed that residents who own cars but have a low car use (postactional stage of the SSBC model) perceive the conflicts more often than residents, who were classified into the first three stages of the behavior change model (H6). This suggests that it was helpful to utilize the SSBC as not the ownership of means of transportation but rather the use and intention for behavior change are essential for the perception of the conflicts. These results are different from Harms et al. (2009) who had discovered that one of the resident groups with the highest perception of conflicts for pedestrians were residents from households without private cars.

5.2 Control variables as critical for the perception of conflicts

Furthermore, the socio-demographic characteristics, which were created as control variables, have a stronger effect on the perception of the conflicts than expected. For example, age is one of the decisive factors for the perception of most conflicts, except for the conflicts from the car driver's perspective. This is similar to the discovery by Harms et al. (2009), who determined that older people were among the residents with the highest awareness of conflicts with parked cars. In the present case study, the elderly in particular perceive the conflicts "Pedestrians are impeded by car traffic and parking" and they have the lowest percentage of bicycle ownership. Walking is an important means of transportation for older people as they manage up to one third of their trips by walking. Thus, having facilities for their daily needs in walking distance is important for their everyday mobility (Infas & DLR, 2019; Oswald & Konopik, 2015; Schwanen & Paez, 2010; Stjernborg, Emilsson, & Ståhl, 2014). Consequently, the advocacy group for the elderly should have an interest in separate bike lanes so that pedestrians do not need to share their space with cyclists and so that the latter do not have to swerve on to sidewalks anymore.

While the elderly perceive the conflicts between pedestrians and cars as well as between pedestrians and cyclists, surprisingly, residents from households with children perceive the conflicts pedestrians may experience on sidewalks with cyclists less often. Thus, residents from households with children do not seem to feel at risk from cyclists. Looking at the residents with children in detail, the data reveals that almost two- thirds of the residents in households with children regularly use a bicycle. For residents without children, the majority (56%) do not cycle regularly. In conclusion, sociodemographic factors seem to be more critical than control variables but illustrate that the ownership and usage of the means of transportation are insufficient to explain the perception of conflicts and there are different resident groups living in the neighborhood.

5.3 Group-serving bias

The results suggest that the residents mostly perceive the conflicts in which they could be involved as the injured party (as a pedestrian or cyclist) and they perceive the conflicts in which they could be the originator of the conflict less often (as a cyclist or car driver). In other words, people are biased and they only see those conflicts that they do not cause. King et al. (2012) found similar group-serving bias for liabilities and responsibilities among cyclists and drivers. Similarly, Coughenour, Abelar, Pharr, Chien, and Singh (2020) discovered that whether car drivers yield to pedestrians at crosswalks depends on the person crossing and on the value of the driver's car.

5.4 Limitations

The explained variances (R²) of some of the models in Table 5 and Table 7 are small. Hence, the conclusions should be read with careful attention. Besides, it needs to be kept in mind that the survey asked the residents to recall conflicts and their experience during traffic participation. Several authors stress the hedonic treadmill effect and recall bias (Mokhtarian & Pendyala, 2018; Viegas de Lima et al., 2018). Individuals adapt their experiences to reduce overly positive or negative experiences and remember their experiences as more neutral when asked about them than during the actual moment. Thus, the perception of the conflicts in the moment themselves may be even more extreme, either less intense or more severe.

5.5 Recommendations for cities and policy makers and further research

The analysis revealed that the current land use and space allocation in cities lead to conflicts, especially between pedestrians and cyclists with parked cars and parking infrastructure as well as between pedestrians and cyclists themselves. The conflicts in which pedestrians are involved are the most controversial as well as the conflicts between pedestrians and cyclists on sidewalks. So, the data in this study suggests that a separate infrastructure for pedestrians and cyclists could help relieve the conflicts. Therefore, urban neighborhoods could give more space to pedestrians and cyclists, and especially dedicate separate infrastructure for the two groups. Such a redesign could include a reallocation of space, for instance through parking control or extensive priced parking. One way for cities to achieve this could be by reusing onstreet parking space for other purposes like wider sidewalks and bike lanes. In the same neighborhood, it was observed that the acceptance of such measurements is higher than often presumed by city officials and policy makers (Kirschner & Lanzendorf, 2020a). Moreover, the risk of conflicts can be reduced when distances between destinations are short so that residents can walk, cycle or use public transportation to get to destinations and do not need to drive (Merlin et al., 2020).

Finally, as "mobility and livability are inexorably intertwined" (Cervero, 2009, p. 224), several authors have pointed to the relationship between parking, conflicts, and the quality of life in neighborhoods. For instance, cities can increase their livability by banning parking on sidewalks (Becker, 2016; Goldman & Gorham, 2006). Thus, we need more research that analyzes the detailed parking-induced conflicts and their relationship with the quality of life in neighborhoods, as well as draw the link for a vision zero for a just, sustainable, and livable city.

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