

Supplemental Material for “Observation of Three Charmonium-Like States with

$$J^{PC} = 1^{--} \text{ in } e^+e^- \rightarrow D^{*0}D^{*-}\pi^+”$$

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I. DETAILS ON EVENT SELECTION

Two-dimensional distributions of $P^*(\pi^0)$ versus $M(\pi^0 D)$ for MC samples with D^0 -tag and D^- -tag methods at $\sqrt{s} = 4.600$ GeV are shown in Fig. 1, respectively.

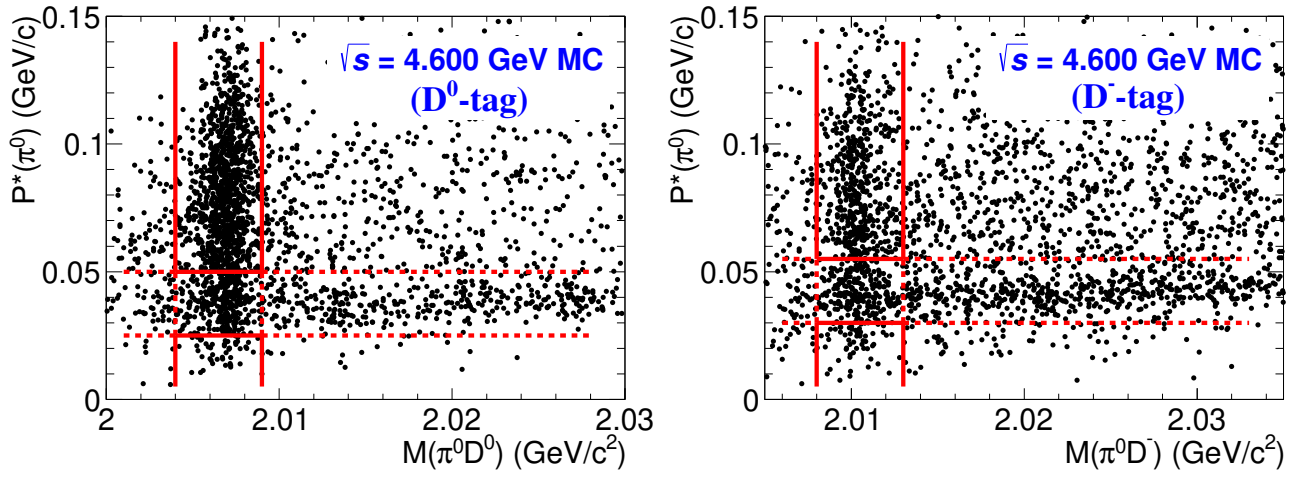


FIG. 1. Two-dimensions distributions of $P^*(\pi^0)$ versus $M(\pi^0 D)$ for MC simulation with D^0 tag and D^- tag methods at $\sqrt{s} = 4.600$ GeV. The events are kept inside the vertical solid lines and vetoed inside the horizontal dashed lines based on the requirements for $M(\pi^0 D)$ and $P^*(\pi^0)$.

II. SIGNAL YIELDS AND BORN CROSS SECTION

A simultaneous fit of D^0 tag and D^- tag is performed at each energy point according to the calculation of the Born cross section.

$$\sigma^{\text{Born}} = \frac{\sigma^{\text{dressed}}}{|1-\Pi|^2} = \frac{N_{D^{0(-)}\text{tag}}^{\text{obs}}}{\mathcal{L}_{\text{int}} \epsilon_{D^{0(-)}\text{tag}} \hat{\mathcal{B}}_{D^{0(-)}\text{tag}} (1 + \delta^{\text{ISR}}) |1-\Pi|^2}.$$

The integral luminosities \mathcal{L}_{int} are measured by Refs. [1-3]. The σ^{Born} is taken as a common parameter in the fitting while detection efficiencies, ISR and vacuum polarization factors are estimated based on MC simulation. With the fit results shown in Tables I and II, $N_{D^0\text{tag}}^{\text{obs}}$ and $N_{D^-\text{tag}}^{\text{obs}}$ can be calculated directly.

TABLE I. The Born cross section of $e^+e^- \rightarrow D^{*0}D^{*-}\pi^+$ for XYZ data sets, where the charge conjugation mode is also included. The first uncertainties are statistical and the second ones systematic.

| \sqrt{s} (GeV) | \mathcal{L}_{int} (pb $^{-1}$) | $1 + \delta^{\text{ISR}}$ | $\frac{1}{ 1-\Pi ^2}$ | $N_{D^0\text{tag}}^{\text{obs}}$ | $\epsilon_{D^0\text{tag}}$ (%) | $N_{D^-\text{tag}}^{\text{obs}}$ | $\epsilon_{D^-\text{tag}}$ (%) | σ^{Born} (pb) |
|------------------|--|---------------------------|-----------------------|----------------------------------|--------------------------------|----------------------------------|--------------------------------|-----------------------------|
| 4.189 | 570.0 | 0.668 | 1.056 | 32.0 \pm 5.5 | 1.1 | 8.3 \pm 1.4 | 1.6 | 44.9 \pm 7.8 \pm 3.5 |
| 4.199 | 526.6 | 0.677 | 1.056 | 62.6 \pm 8.6 | 2.0 | 13.4 \pm 1.8 | 2.6 | 48.5 \pm 6.7 \pm 3.8 |
| 4.209 | 572.1 | 0.697 | 1.057 | 193.3 \pm 14.2 | 2.9 | 37.5 \pm 2.7 | 3.3 | 94.4 \pm 6.9 \pm 7.5 |
| 4.219 | 569.2 | 0.725 | 1.056 | 291.0 \pm 17.1 | 3.6 | 55.0 \pm 3.2 | 4.0 | 110.2 \pm 6.5 \pm 8.7 |
| 4.226 | 1111.9 | 0.749 | 1.056 | 1173.5 \pm 42.1 | 4.3 | 173.9 \pm 6.2 | 4.8 | 145.6 \pm 5.2 \pm 11.5 |
| 4.236 | 530.3 | 0.770 | 1.056 | 468.0 \pm 24.1 | 4.2 | 88.5 \pm 4.6 | 4.8 | 151.7 \pm 7.8 \pm 11.5 |
| 4.242 | 55.9 | 0.780 | 1.055 | 51.6 \pm 8.9 | 5.4 | 9.7 \pm 1.7 | 6.1 | 122.3 \pm 21.2 \pm 8.5 |
| 4.244 | 538.1 | 0.784 | 1.056 | 522.4 \pm 26.6 | 5.3 | 98.5 \pm 5.0 | 6.0 | 130.4 \pm 6.6 \pm 9.0 |
| 4.258 | 828.4 | 0.795 | 1.054 | 1077.9 \pm 37.9 | 5.5 | 162.8 \pm 5.7 | 6.2 | 132.6 \pm 4.7 \pm 10.8 |
| 4.267 | 531.1 | 0.799 | 1.053 | 571.3 \pm 28.2 | 4.6 | 109.5 \pm 5.4 | 5.3 | 163.6 \pm 8.1 \pm 11.6 |
| 4.278 | 175.7 | 0.803 | 1.053 | 177.7 \pm 16.1 | 4.6 | 34.1 \pm 3.1 | 5.2 | 153.7 \pm 13.9 \pm 10.9 |
| 4.287 | 494.2 | 0.803 | 1.053 | 578.5 \pm 27.7 | 5.8 | 109.9 \pm 5.3 | 6.5 | 141.8 \pm 6.8 \pm 10.4 |
| 4.308 | 45.1 | 0.802 | 1.052 | 85.0 \pm 11.1 | 5.5 | 16.3 \pm 2.1 | 6.3 | 239.0 \pm 31.3 \pm 19.1 |
| 4.311 | 494.3 | 0.802 | 1.052 | 745.5 \pm 33.2 | 5.5 | 143.8 \pm 6.4 | 6.3 | 193.7 \pm 8.6 \pm 15.5 |
| 4.337 | 506.1 | 0.798 | 1.051 | 1078.9 \pm 42.2 | 7.4 | 201.5 \pm 7.9 | 8.2 | 203.7 \pm 8.0 \pm 19.6 |
| 4.358 | 543.9 | 0.798 | 1.051 | 1604.8 \pm 50.2 | 8.0 | 304.4 \pm 9.5 | 9.0 | 262.3 \pm 8.2 \pm 20.1 |
| 4.377 | 524.7 | 0.795 | 1.051 | 1909.7 \pm 55.2 | 6.0 | 367.6 \pm 10.6 | 6.8 | 431.5 \pm 12.5 \pm 35.9 |
| 4.387 | 55.6 | 0.794 | 1.051 | 234.1 \pm 19.2 | 7.8 | 45.2 \pm 3.7 | 8.9 | 384.3 \pm 31.5 \pm 28.0 |
| 4.395 | 508.2 | 0.792 | 1.051 | 2421.6 \pm 60.0 | 7.6 | 466.1 \pm 11.5 | 8.7 | 446.5 \pm 11.1 \pm 32.5 |
| 4.416 | 1090.7 | 0.794 | 1.052 | 6225.0 \pm 95.7 | 7.4 | 1185.2 \pm 18.2 | 8.3 | 547.7 \pm 8.4 \pm 38.5 |
| 4.436 | 570.6 | 0.796 | 1.054 | 3798.9 \pm 74.6 | 7.6 | 755.4 \pm 14.8 | 9.0 | 619.3 \pm 12.2 \pm 42.2 |
| 4.467 | 111.1 | 0.810 | 1.055 | 929.9 \pm 35.9 | 7.8 | 176.2 \pm 6.8 | 8.8 | 742.9 \pm 28.7 \pm 50.8 |
| 4.527 | 112.1 | 0.863 | 1.054 | 1128.2 \pm 39.2 | 8.4 | 217.5 \pm 7.5 | 9.7 | 776.7 \pm 27.0 \pm 60.5 |
| 4.575 | 48.9 | 0.900 | 1.054 | 430.3 \pm 25.1 | 10.2 | 86.1 \pm 5.0 | 12.1 | 537.1 \pm 31.4 \pm 36.4 |
| 4.600 | 586.9 | 0.905 | 1.055 | 5964.6 \pm 95.1 | 10.4 | 1206.9 \pm 19.2 | 12.5 | 606.4 \pm 9.7 \pm 41.2 |
| 4.613 | 103.7 | 0.908 | 1.055 | 1019.2 \pm 38.9 | 9.9 | 210.1 \pm 8.0 | 12.1 | 613.4 \pm 23.4 \pm 41.2 |
| 4.628 | 521.5 | 0.903 | 1.054 | 5115.1 \pm 88.6 | 10.2 | 1026.4 \pm 17.8 | 12.1 | 599.2 \pm 10.4 \pm 40.5 |
| 4.641 | 551.7 | 0.900 | 1.054 | 5404.6 \pm 90.2 | 10.0 | 1123.5 \pm 18.7 | 12.4 | 608.4 \pm 10.1 \pm 44.4 |
| 4.661 | 529.4 | 0.893 | 1.054 | 5434.9 \pm 91.8 | 10.1 | 1111.6 \pm 18.8 | 12.2 | 641.7 \pm 10.8 \pm 47.1 |
| 4.682 | 1667.4 | 0.894 | 1.054 | 18143.7 \pm 168.0 | 10.6 | 3743.9 \pm 34.7 | 12.9 | 647.2 \pm 6.0 \pm 45.3 |
| 4.699 | 535.5 | 0.900 | 1.055 | 6088.0 \pm 97.2 | 10.4 | 1265.0 \pm 20.2 | 12.9 | 680.3 \pm 10.9 \pm 48.9 |
| 4.740 | 163.9 | 0.925 | 1.055 | 1761.7 \pm 54.3 | 11.0 | 374.8 \pm 11.5 | 13.9 | 595.0 \pm 18.3 \pm 43.3 |
| 4.750 | 366.6 | 0.934 | 1.055 | 3902.4 \pm 80.9 | 11.0 | 824.4 \pm 17.1 | 13.8 | 580.0 \pm 12.0 \pm 40.9 |
| 4.781 | 511.5 | 0.957 | 1.055 | 5185.2 \pm 95.2 | 10.9 | 1113.7 \pm 20.4 | 13.9 | 546.8 \pm 10.0 \pm 36.6 |
| 4.843 | 525.2 | 0.979 | 1.056 | 4539.6 \pm 91.7 | 10.6 | 972.9 \pm 19.7 | 13.4 | 468.4 \pm 9.5 \pm 33.1 |
| 4.918 | 207.8 | 0.973 | 1.056 | 1674.8 \pm 55.2 | 10.4 | 370.3 \pm 12.2 | 13.6 | 448.7 \pm 14.8 \pm 31.8 |
| 4.951 | 159.3 | 0.965 | 1.056 | 1273.9 \pm 39.5 | 10.3 | 283.3 \pm 8.8 | 13.5 | 452.9 \pm 14.1 \pm 31.1 |

TABLE II. The Born cross section of $e^+e^- \rightarrow D^{*0}D^{*-}\pi^+$ for Scan data sets, where the charge conjugation mode is also included. The first uncertainties are statistical and the second ones systematic.

| \sqrt{s} (GeV) | \mathcal{L}_{int} (pb $^{-1}$) | $1 + \delta^{\text{ISR}}$ | $\frac{1}{ 1-\Pi ^2}$ | $N_{D^0\text{tag}}^{\text{obs}}$ | $\epsilon_{D^0\text{tag}}$ (%) | $N_{D^-\text{tag}}^{\text{obs}}$ | $\epsilon_{D^-\text{tag}}$ (%) | σ^{Born} (pb) |
|------------------|--|---------------------------|-----------------------|----------------------------------|--------------------------------|----------------------------------|--------------------------------|-----------------------------|
| 4.200 | 6.8 | 0.677 | 1.057 | 2.9 ± 1.8 | 2.3 | 0.6 ± 0.4 | 2.8 | $156.2 \pm 94.9 \pm 12.3$ |
| 4.203 | 7.6 | 0.681 | 1.057 | 3.4 ± 1.9 | 2.5 | 0.7 ± 0.4 | 3.0 | $146.3 \pm 82.4 \pm 11.6$ |
| 4.207 | 7.7 | 0.691 | 1.057 | 3.7 ± 2.1 | 2.9 | 0.7 ± 0.4 | 3.3 | $134.3 \pm 78.2 \pm 10.6$ |
| 4.212 | 7.8 | 0.705 | 1.057 | 4.2 ± 2.2 | 3.2 | 0.8 ± 0.4 | 3.7 | $134.6 \pm 69.6 \pm 10.6$ |
| 4.217 | 7.9 | 0.720 | 1.056 | 6.0 ± 2.5 | 3.8 | 1.1 ± 0.5 | 4.2 | $158.1 \pm 65.7 \pm 12.5$ |
| 4.222 | 8.2 | 0.738 | 1.056 | 6.5 ± 3.1 | 4.0 | 1.2 ± 0.6 | 4.4 | $150.2 \pm 70.8 \pm 11.9$ |
| 4.227 | 8.2 | 0.751 | 1.056 | 5.9 ± 2.6 | 4.2 | 1.1 ± 0.5 | 4.7 | $128.8 \pm 56.6 \pm 10.2$ |
| 4.232 | 8.3 | 0.762 | 1.056 | 7.0 ± 3.0 | 4.2 | 1.3 ± 0.6 | 4.7 | $148.8 \pm 64.0 \pm 11.8$ |
| 4.237 | 7.8 | 0.773 | 1.055 | 3.5 ± 2.9 | 5.0 | 0.7 ± 0.5 | 5.6 | $65.0 \pm 53.7 \pm 4.5$ |
| 4.240 | 8.6 | 0.778 | 1.055 | 10.0 ± 4.1 | 5.2 | 1.8 ± 0.8 | 5.6 | $163.5 \pm 67.2 \pm 11.3$ |
| 4.242 | 8.5 | 0.781 | 1.056 | 8.1 ± 3.3 | 5.5 | 1.5 ± 0.6 | 5.8 | $125.4 \pm 51.2 \pm 8.7$ |
| 4.245 | 8.6 | 0.784 | 1.056 | 11.7 ± 3.7 | 5.5 | 2.2 ± 0.7 | 6.0 | $179.1 \pm 57.1 \pm 12.4$ |
| 4.247 | 8.6 | 0.787 | 1.055 | 14.9 ± 3.7 | 5.6 | 2.7 ± 0.7 | 6.1 | $219.5 \pm 55.3 \pm 15.2$ |
| 4.252 | 8.7 | 0.792 | 1.054 | 5.3 ± 2.9 | 5.3 | 1.0 ± 0.5 | 5.9 | $81.9 \pm 45.1 \pm 6.7$ |
| 4.257 | 8.9 | 0.795 | 1.054 | 10.7 ± 4.3 | 5.4 | 2.1 ± 0.8 | 6.1 | $157.6 \pm 62.8 \pm 12.8$ |
| 4.262 | 8.6 | 0.796 | 1.053 | 16.9 ± 3.9 | 4.6 | 3.2 ± 0.7 | 5.1 | $300.1 \pm 68.9 \pm 21.2$ |
| 4.267 | 8.6 | 0.798 | 1.053 | 5.2 ± 3.4 | 4.7 | 1.0 ± 0.6 | 5.2 | $90.8 \pm 60.1 \pm 6.4$ |
| 4.272 | 8.6 | 0.800 | 1.053 | 7.7 ± 3.2 | 4.7 | 1.5 ± 0.6 | 5.4 | $133.5 \pm 55.9 \pm 9.4$ |
| 4.277 | 8.7 | 0.800 | 1.053 | 10.2 ± 4.3 | 5.9 | 1.9 ± 0.8 | 6.7 | $139.0 \pm 57.7 \pm 9.8$ |
| 4.282 | 8.6 | 0.803 | 1.053 | 16.0 ± 3.9 | 6.1 | 3.0 ± 0.7 | 6.7 | $214.0 \pm 52.4 \pm 15.7$ |
| 4.287 | 9.0 | 0.802 | 1.053 | 9.1 ± 4.0 | 6.1 | 1.7 ± 0.8 | 6.8 | $117.6 \pm 51.4 \pm 8.6$ |
| 4.297 | 8.5 | 0.801 | 1.052 | 15.9 ± 4.9 | 5.5 | 2.9 ± 0.9 | 6.0 | $242.0 \pm 74.9 \pm 19.3$ |
| 4.307 | 8.6 | 0.803 | 1.052 | 10.9 ± 4.2 | 5.4 | 2.1 ± 0.8 | 6.2 | $163.2 \pm 62.5 \pm 13.0$ |
| 4.317 | 9.3 | 0.801 | 1.052 | 3.7 ± 3.6 | 5.9 | 0.8 ± 0.7 | 6.5 | $53.4 \pm 46.1 \pm 4.3$ |
| 4.327 | 8.7 | 0.800 | 1.051 | 30.2 ± 6.9 | 7.4 | 5.7 ± 1.3 | 8.2 | $333.1 \pm 75.9 \pm 32.0$ |
| 4.337 | 8.7 | 0.798 | 1.051 | 18.2 ± 6.0 | 7.4 | 3.4 ± 1.1 | 8.2 | $199.9 \pm 65.6 \pm 19.2$ |
| 4.347 | 8.5 | 0.798 | 1.051 | 23.8 ± 6.4 | 7.8 | 4.3 ± 1.2 | 8.4 | $251.9 \pm 68.0 \pm 19.3$ |
| 4.357 | 8.1 | 0.797 | 1.051 | 36.9 ± 7.2 | 7.6 | 6.9 ± 1.3 | 8.4 | $428.1 \pm 83.0 \pm 32.8$ |
| 4.367 | 8.5 | 0.796 | 1.051 | 23.0 ± 7.2 | 6.1 | 4.2 ± 1.3 | 6.6 | $316.5 \pm 99.5 \pm 26.3$ |
| 4.377 | 8.2 | 0.796 | 1.051 | 29.9 ± 7.1 | 6.2 | 5.7 ± 1.4 | 7.0 | $421.9 \pm 99.7 \pm 35.1$ |
| 4.387 | 7.5 | 0.794 | 1.051 | 40.2 ± 8.1 | 7.9 | 7.3 ± 1.5 | 8.5 | $487.6 \pm 98.4 \pm 35.5$ |
| 4.392 | 7.4 | 0.794 | 1.051 | 37.5 ± 7.7 | 7.9 | 7.2 ± 1.5 | 8.9 | $454.6 \pm 93.3 \pm 33.1$ |
| 4.397 | 7.2 | 0.793 | 1.051 | 38.3 ± 7.8 | 8.0 | 7.2 ± 1.5 | 9.0 | $471.3 \pm 96.1 \pm 34.3$ |
| 4.407 | 6.4 | 0.793 | 1.052 | 36.3 ± 7.7 | 7.3 | 6.9 ± 1.5 | 8.2 | $558.4 \pm 118.7 \pm 39.2$ |
| 4.417 | 7.5 | 0.793 | 1.052 | 37.4 ± 8.2 | 7.5 | 7.1 ± 1.6 | 8.4 | $473.1 \pm 103.7 \pm 33.2$ |
| 4.422 | 7.4 | 0.793 | 1.052 | 43.9 ± 8.2 | 7.4 | 8.3 ± 1.6 | 8.3 | $564.9 \pm 106.1 \pm 39.7$ |
| 4.427 | 6.8 | 0.794 | 1.053 | 42.0 ± 8.0 | 8.7 | 8.1 ± 1.5 | 9.9 | $503.3 \pm 95.9 \pm 34.3$ |
| 4.437 | 7.6 | 0.796 | 1.054 | 52.5 ± 9.3 | 8.0 | 10.3 ± 1.8 | 9.3 | $609.9 \pm 108.1 \pm 41.6$ |
| 4.447 | 7.7 | 0.800 | 1.054 | 67.7 ± 9.8 | 7.3 | 12.8 ± 1.9 | 8.2 | $845.9 \pm 123.1 \pm 57.7$ |
| 4.457 | 8.7 | 0.803 | 1.055 | 69.9 ± 10.3 | 7.4 | 13.5 ± 2.0 | 8.5 | $756.7 \pm 111.1 \pm 51.7$ |
| 4.477 | 8.2 | 0.816 | 1.055 | 85.4 ± 11.0 | 7.9 | 15.6 ± 2.0 | 8.6 | $909.9 \pm 117.0 \pm 62.2$ |
| 4.497 | 8.0 | 0.833 | 1.055 | 81.6 ± 10.8 | 7.9 | 15.6 ± 2.1 | 8.9 | $874.1 \pm 116.0 \pm 59.7$ |
| 4.517 | 8.7 | 0.855 | 1.055 | 73.6 ± 10.8 | 8.2 | 13.9 ± 2.0 | 9.1 | $682.5 \pm 100.3 \pm 53.2$ |
| 4.537 | 9.3 | 0.875 | 1.054 | 101.3 ± 12.3 | 9.4 | 20.1 ± 2.4 | 11.1 | $739.8 \pm 89.7 \pm 57.6$ |
| 4.547 | 8.8 | 0.884 | 1.054 | 92.0 ± 11.8 | 9.6 | 18.2 ± 2.3 | 11.2 | $697.0 \pm 89.7 \pm 54.3$ |
| 4.557 | 8.3 | 0.892 | 1.054 | 90.9 ± 11.3 | 9.8 | 17.9 ± 2.2 | 11.5 | $704.7 \pm 87.8 \pm 47.8$ |
| 4.567 | 8.4 | 0.897 | 1.054 | 96.5 ± 12.3 | 9.8 | 19.0 ± 2.4 | 11.4 | $737.6 \pm 94.2 \pm 50.0$ |
| 4.577 | 8.5 | 0.901 | 1.055 | 78.7 ± 11.3 | 9.7 | 15.8 ± 2.3 | 11.6 | $591.7 \pm 84.7 \pm 40.1$ |
| 4.587 | 8.2 | 0.905 | 1.055 | 83.3 ± 11.6 | 9.9 | 16.6 ± 2.3 | 11.7 | $639.5 \pm 89.1 \pm 43.4$ |

III. MULTIPLE SOLUTIONS OF LINESHAPE FIT

The dressed cross section is parameterized as the coherent sum of a continuum amplitude for $e^+e^- \rightarrow D^{*0}D^{*-}\pi^+$ and three $R_k \rightarrow D^{*0}D^{*-}\pi^+$ resonance amplitudes:

$$\sigma^{\text{dressed}}(\sqrt{s}) = C_0|C_1\sqrt{\Phi(\sqrt{s}) + \sum_{k=1}^3 \text{BW}_k(\sqrt{s})e^{i\phi_k}|^2,$$

where the relativistic Breit-Wigner functions are given by

$$\text{BW}_k(\sqrt{s}) = \frac{m_k}{\sqrt{s}} \frac{\sqrt{12\pi\Gamma_k^{ee}\mathcal{B}_k\Gamma_k^{\text{tot}}}}{s - m_k^2 + im_k\Gamma_k^{\text{tot}}} \sqrt{\frac{\Phi(\sqrt{s})}{\Phi(m_k)}},$$

and the 3-body phase space contribution $\Phi(\sqrt{s}) = \iint \frac{1}{(2\pi)^3 32(\sqrt{s})^3} dm_{23}^2 dm_{12}^2$. All the parameters in the fit are free except for $C_0 = 3.894 \times 10^5 \text{ nb GeV}^2$ as a unit conversion factor.

In the above function, mathematically there exists eight solutions with the same outputs of the dressed cross sections [7], which is due to the interference between any two of the involved components in the fitting function. The different combinations of the amplitude and relative phase angle of each component can lead to the same outcome, whose sizes are presented by the parameters $\Gamma_k^{ee}\mathcal{B}_k$ and ϕ_k , respectively. This means that there are eight degenerate solutions with the same fit quality, as shown in Fig. 2. Among them, the results of the resonance masses m_k and total widths Γ_k^{tot} in the multiple solutions are equal, while those of the partial width and relative phase angle vary.

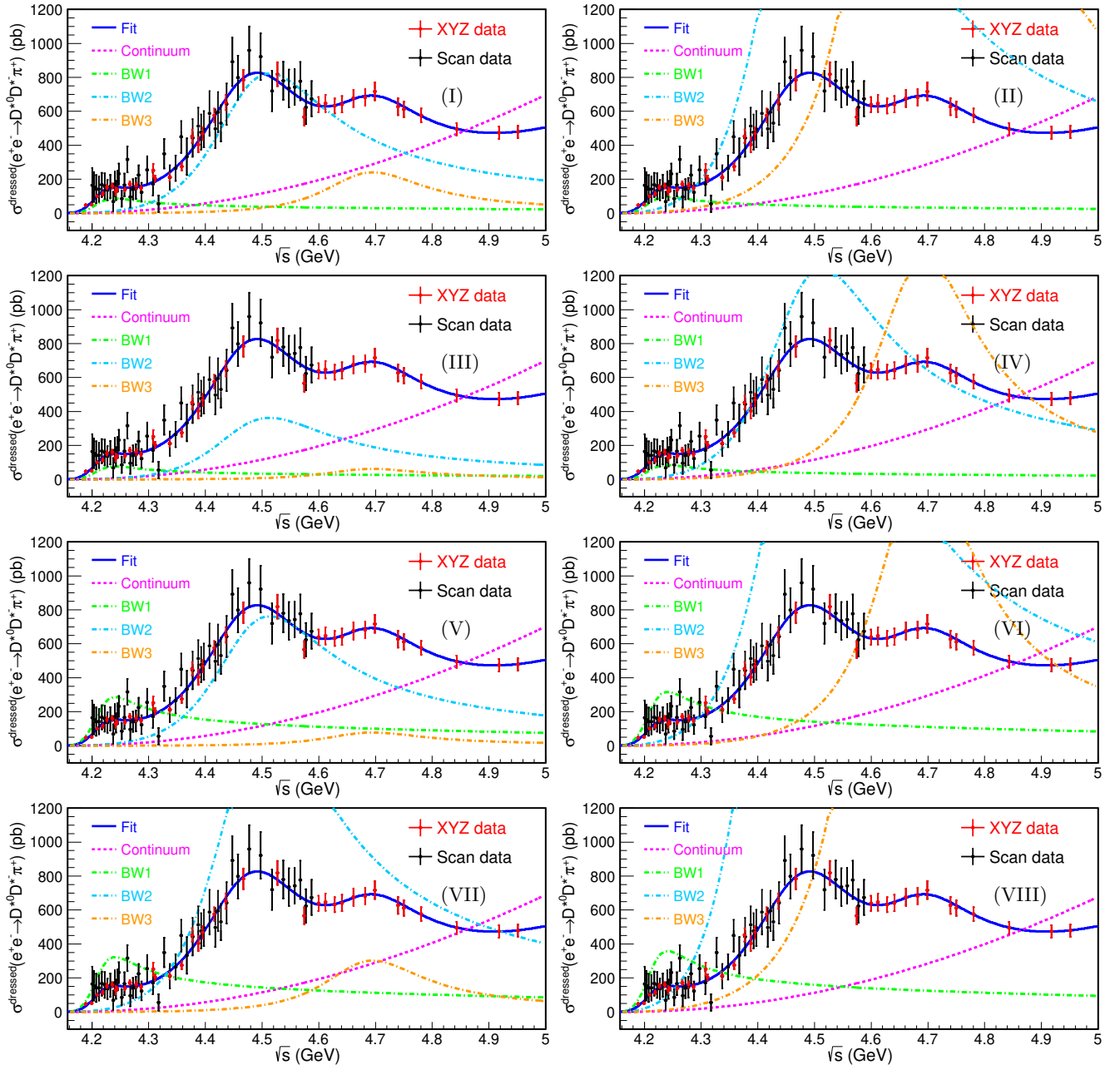


FIG. 2. The fit results of the dressed cross section lineshape of $e^+e^- \rightarrow D^{*0}D^{*-}\pi^+$, where the charge conjugation mode is also included. The black and red points with error bars are data, including statistical and systematic uncertainties. The blue curve is the total fit. The green, azure and orange dashed curves describe three BW functions, and the pink dashed-curve is the three body phase space contribution.

IV. SYSTEMATIC UNCERTAINTIES

The systematic uncertainty studies are performed at energy points where the signal yield is larger than 500 events. For other points suffering limited statistics, the uncertainty from the closest point is taken as its systematic uncertainty. All the systematic uncertainties are studied on each tag method separately and then combined together according to their yields. To consider all the related systematic uncertainties in the measurement of the Born cross sections, the sources of systematic uncertainty are divided into three categories.

The first category includes uncertainties associated with the detection efficiencies, such as tracking, particle identification, π^0 reconstruction, signal region requirements of the reconstructed unstable particles (*i.e.*, the $P^*(\pi^0)$ momentum rejection region, $D^0(D^-)$ and $D^{*0}(D^{*-})$ mass window requirements), MC simulation model and ISR correction factors. The uncertainty of detection and PID efficiency is 1.0% for each charged track [4], and 2.0% for π^0 reconstruction [5]. The uncertainties associated with the $P^*(\pi^0)$, $M(D^0(D^-))$ and $M(D^{*0}(D^{*-}))$ windows are estimated by re-extracting the detection efficiencies with Gaussian-smearred MC samples where the Gaussian parameters are obtained from the discrepancies between data and MC simulation. The MC samples are corrected according to the partial-wave-analysis (PWA) results at each energy point. To estimate the uncertainties from PWA-corrected MC samples, the samples with different PWA results are re-corrected by changing the possible components used in the PWA. The differences of efficiencies extracted from nominal and re-corrected MC samples are taken as the systematic uncertainty of the signal model. The ISR correction factors can have an impact on the detection efficiencies by affecting the slope of the lineshape, and hence, they are treated together as $(1 + \delta^{\text{ISR}})\epsilon$. Since the ISR correction factors are estimated by the fitting-iteration method, the uncertainty of this item comes from four different parts: the differences between the last two iterations are taken as the uncertainty of the iteration method itself; the uncertainty from the lineshape fitting model used in the iteration are estimated by replacing the phase space model with a parameterized function; the uncertainty of $(1 + \delta^{\text{ISR}})\epsilon$ is estimated by 500 groups of cross-section toys which are re-sampled according to the uncertainty of the parameters and the corresponding covariance matrix; the vacuum polarization factors are taken from QED calculations at each energy point and affect the slope of the lineshape with an estimated uncertainty of 0.5%.

The second category includes uncertainties associated with the signal shape, background shape and fit range, which affect the estimation of signal yields. The uncertainty of the signal shape is estimated by convolving it with a double-Gaussian function in the fit instead of a single Gaussian function in the nominal results. The description of the background shape is changed from a 2nd order Chebyshev function to a linear function in the fit and the differences between the two cases are considered as the uncertainty. The uncertainty associated with the fit range uncertainty is determined by altering the fit range from (1.91, 2.12) GeV/ c^2 to (1.911, 2.12) GeV/ c^2 .

The last category includes the luminosity and quoted BF's, where the former uncertainty is 1.0% at each energy point [1–3], and the latter uncertainties are taken from the PDG [6].

Assuming no significant correlations between sources, the total systematic uncertainty is obtained as the sum in quadrature. Table III summarizes the systematic uncertainties of the cross section at various energy points.

TABLE III. The summary of all the systematic uncertainties (%) in the Born cross section measurement. The items marked with ‘†’ are treated as fully correlated uncertainties, while others are uncorrelated uncertainties.

| \sqrt{s} (GeV) | Track† | PID† | π^0 † | Signal region | Decay Model | $(1 + \delta^{\text{ISR}})$ † | Signal shape | Bkg. shape | Fit range | $\mathcal{L}_{\text{int}}^\dagger$ | \mathcal{B}^\dagger | Total |
|------------------|--------|------|-----------|---------------|-------------|-------------------------------|--------------|------------|-----------|------------------------------------|-----------------------|-------|
| 4.226 | 3.7 | 3.7 | 2.8 | 0.5 | 0.9 | 1.4 | 2.5 | 0.9 | 3.1 | 1.0 | 2.7 | 7.9 |
| 4.236 | 3.7 | 3.7 | 2.7 | 0.4 | 0.3 | 1.0 | 2.3 | 0.5 | 2.6 | 1.0 | 2.7 | 7.6 |
| 4.244 | 3.6 | 3.6 | 2.8 | 0.6 | 0.6 | 0.8 | 1.0 | 1.2 | 1.3 | 1.0 | 2.7 | 6.9 |
| 4.258 | 3.6 | 3.6 | 2.8 | 0.6 | 0.0 | 0.7 | 2.6 | 2.5 | 3.2 | 1.0 | 2.7 | 8.1 |
| 4.267 | 3.6 | 3.6 | 2.8 | 0.7 | 0.1 | 0.7 | 1.8 | 0.5 | 1.8 | 1.0 | 2.7 | 7.1 |
| 4.288 | 3.7 | 3.7 | 2.8 | 0.2 | 0.1 | 1.9 | 1.6 | 1.6 | 1.6 | 1.0 | 2.7 | 7.3 |
| 4.312 | 3.6 | 3.6 | 2.7 | 0.3 | 0.6 | 2.9 | 1.6 | 3.0 | 1.5 | 1.0 | 2.6 | 8.0 |
| 4.337 | 3.6 | 3.6 | 2.7 | 0.4 | 0.5 | 2.3 | 1.9 | 6.0 | 2.1 | 1.0 | 2.7 | 9.6 |
| 4.358 | 3.7 | 3.7 | 2.8 | 0.5 | 0.1 | 2.3 | 1.3 | 2.5 | 1.7 | 1.0 | 2.7 | 7.7 |
| 4.377 | 3.7 | 3.7 | 2.7 | 0.4 | 0.4 | 1.2 | 0.9 | 4.6 | 1.7 | 1.0 | 2.7 | 8.3 |
| 4.397 | 3.7 | 3.7 | 2.8 | 0.3 | 0.6 | 0.6 | 0.9 | 2.7 | 0.8 | 1.0 | 2.7 | 7.3 |
| 4.416 | 3.7 | 3.7 | 2.7 | 0.6 | 0.4 | 0.8 | 0.2 | 2.3 | 0.5 | 1.0 | 2.7 | 7.0 |
| 4.436 | 3.7 | 3.7 | 2.8 | 0.3 | 0.2 | 0.9 | 1.2 | 1.3 | 0.0 | 1.0 | 2.7 | 6.8 |
| 4.467 | 3.7 | 3.7 | 2.7 | 0.5 | 0.6 | 1.0 | 0.3 | 1.5 | 0.4 | 1.0 | 2.7 | 6.8 |
| 4.527 | 3.7 | 3.7 | 2.7 | 0.4 | 0.4 | 0.9 | 3.1 | 1.0 | 2.5 | 1.0 | 2.7 | 7.8 |
| 4.575 | 3.7 | 3.7 | 2.8 | 0.5 | 0.3 | 0.6 | 1.1 | 0.6 | 0.4 | 1.0 | 2.7 | 6.8 |
| 4.600 | 3.7 | 3.7 | 2.7 | 0.5 | 1.2 | 0.9 | 0.5 | 0.3 | 0.7 | 1.0 | 2.6 | 6.8 |
| 4.612 | 3.7 | 3.7 | 2.8 | 0.2 | 0.4 | 1.1 | 0.5 | 0.7 | 0.5 | 1.0 | 2.7 | 6.7 |
| 4.628 | 3.7 | 3.7 | 2.7 | 0.4 | 0.1 | 1.3 | 0.7 | 0.9 | 0.4 | 1.0 | 2.6 | 6.8 |
| 4.641 | 3.7 | 3.7 | 2.7 | 0.3 | 1.0 | 2.7 | 0.7 | 1.1 | 0.8 | 1.0 | 2.7 | 7.3 |
| 4.661 | 3.7 | 3.7 | 2.8 | 0.3 | 2.0 | 2.6 | 0.6 | 0.3 | 0.1 | 1.0 | 2.7 | 7.3 |
| 4.681 | 3.7 | 3.7 | 2.7 | 0.3 | 0.5 | 2.4 | 0.2 | 0.5 | 0.1 | 1.0 | 2.7 | 7.0 |
| 4.698 | 3.7 | 3.7 | 2.7 | 0.2 | 1.0 | 2.5 | 0.1 | 1.1 | 0.4 | 1.0 | 2.7 | 7.2 |
| 4.740 | 3.7 | 3.7 | 2.7 | 0.5 | 2.5 | 1.5 | 0.5 | 0.8 | 0.8 | 1.0 | 2.6 | 7.3 |
| 4.750 | 3.7 | 3.7 | 2.7 | 0.3 | 2.1 | 1.0 | 0.1 | 0.6 | 0.5 | 1.0 | 2.6 | 7.0 |
| 4.781 | 3.7 | 3.7 | 2.7 | 0.4 | 0.4 | 0.8 | 0.2 | 0.4 | 0.9 | 1.0 | 2.6 | 6.7 |
| 4.843 | 3.7 | 3.7 | 2.7 | 0.2 | 2.1 | 1.2 | 0.4 | 0.9 | 0.6 | 1.0 | 2.6 | 7.1 |
| 4.918 | 3.7 | 3.7 | 2.7 | 0.4 | 1.8 | 1.2 | 0.4 | 1.4 | 0.5 | 1.0 | 2.6 | 7.1 |
| 4.951 | 3.7 | 3.7 | 2.8 | 0.4 | 0.6 | 0.8 | 0.6 | 1.6 | 0.6 | 1.0 | 2.7 | 6.9 |

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